

Terms used in Compression Springs

1. Solid length. When the compression spring is compressed until the coils come in contact with each other, then the spring is said to be *solid*. **The solid length of a spring is the product of total** number of coils and the diameter of the wire. Mathematically,

Solid length of the spring,

$$LS = n'.d$$

where n' = Total number of coils, and

d = Diameter of the wire.

2. Free length. The free length of a compression spring, as shown in Fig., is **the length of** the spring in the free or unloaded condition. It is equal to the solid length plus the maximum deflection or compression of the spring and the clearance between the adjacent coils (when fully compressed).

Mathematically,

Free length of the spring,

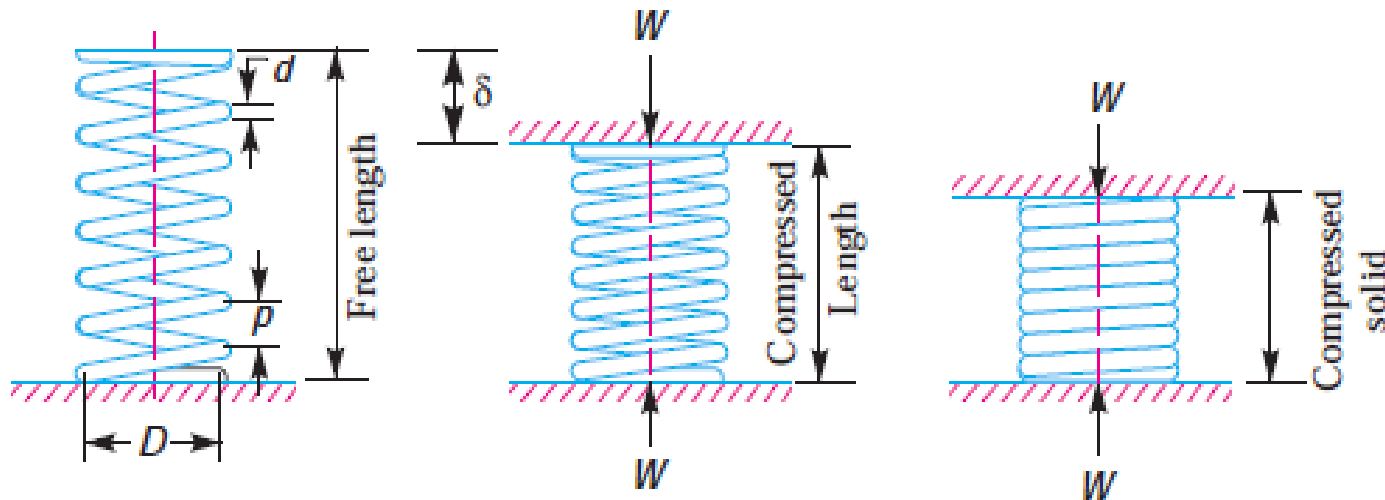
$$L_F = \text{Solid length} + \text{Maximum compression} + \text{*Clearance between adjacent coils (or clash allowance)}$$

$$= n'.d + \delta_{max} + 0.15 \delta_{max}$$

The following relation may also be used to find the free length of the spring, *i.e.*

$$L_F = n'.d + \delta_{max} + (n' - 1) \times 1 \text{ mm}$$

In this expression, the clearance between the two adjacent coils is taken as 1 mm.



3. *Spring index. The spring index is defined as the ratio of the mean diameter of the coil to the diameter of the wire. Mathematically,*

$$\text{Spring index, } C = D / d$$

where $D = \text{Mean diameter of the coil}$, and
 $d = \text{Diameter of the wire}$.

4. *Spring rate. The spring rate (or stiffness or spring constant) is defined as the load required per unit deflection of the spring. Mathematically,*

$$\text{Spring rate, } k = W / \delta$$

where $W = \text{Load}$, and
 $\delta = \text{Deflection of the spring}$.

5. Pitch. *The pitch of the coil is defined as the axial distance between adjacent coils in uncompressed state. Mathematically,*

$$\text{Pitch of the coil, } p = \frac{\text{Free length}}{n' - 1}$$

The pitch of the coil may also be obtained by using the following relation, *i.e.*

$$\text{Pitch of the coil, } p = \frac{L_F - L_S}{n'} + d$$

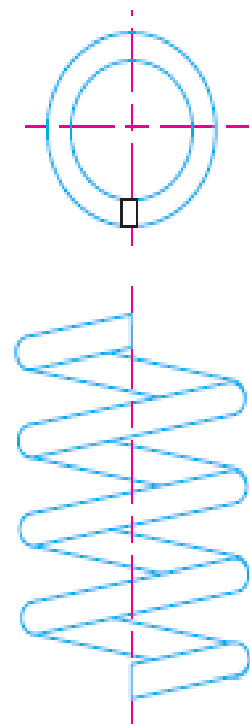
where $L_F =$ *Free length of the spring,*

$L_S =$ *Solid length of the spring,*

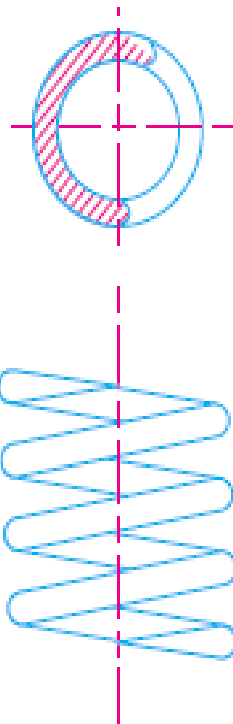
$n' =$ *Total number of coils, and*

$d =$ *Diameter of the wire.*

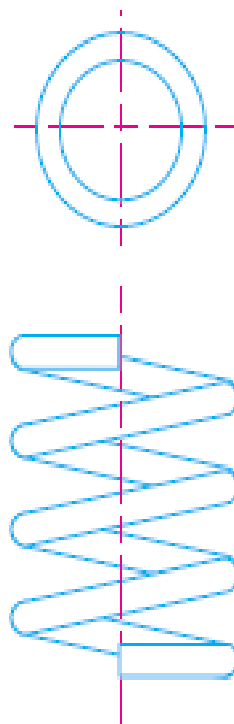
End Connections for Compression Helical Springs



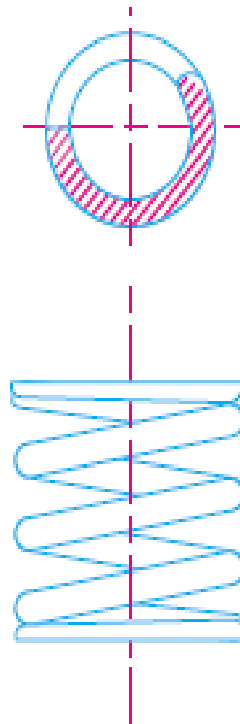
(a) Plain ends.



(b) Ground ends.



(c) Squared ends.



(d) Squared and ground ends.

<i>Type of end</i>	<i>Total number of turns (n')</i>	<i>Solid length</i>	<i>Free length</i>
1. Plain ends	n	$(n + 1) d$	$p \times n + d$
2. Ground ends	n	$n \times d$	$p \times n$
3. Squared ends	$n + 2$	$(n + 3) d$	$p \times n + 3d$
4. Squared and ground ends	$n + 2$	$(n + 2) d$	$p \times n + 2d$

Stresses in Helical Springs of Circular Wire

Consider a helical compression spring made of circular wire and subjected to an axial load W , as shown in Fig.

Let D = Mean diameter of the spring coil,

d = Diameter of the spring wire,

n = Number of active coils,

G = Modulus of rigidity for the spring material,

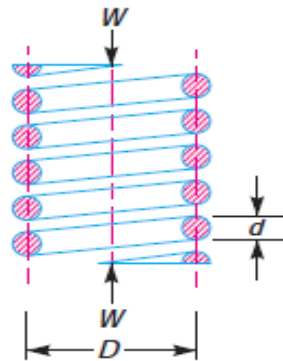
W = Axial load on the spring,

τ = Maximum shear stress induced in the wire,

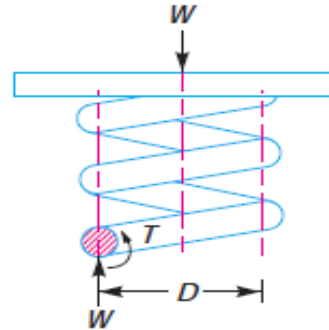
C = Spring index = D/d ,

p = Pitch of the coils, and

δ = Deflection of the spring, as a result of an axial load W .



(a) Axially loaded helical spring.



(b) Free body diagram showing that wire is subjected to torsional shear and a direct shear.

Now consider a part of the compression spring as shown in Fig (b). The load W tends to rotate the wire due to the twisting moment (T) set up in the wire. Thus torsional shear stress is induced in the wire.

A little consideration will show that part of the spring, as shown in Fig (b), is in equilibrium under the action of two forces W and the twisting moment T . We know that the twisting moment,

$$T = W \times \frac{D}{2} = \frac{\pi}{16} \times \tau_1 \times d^3$$

$$\tau_1 = \frac{8WD}{\pi d^3}$$

The torsional shear stress diagram is shown in Fig (a).

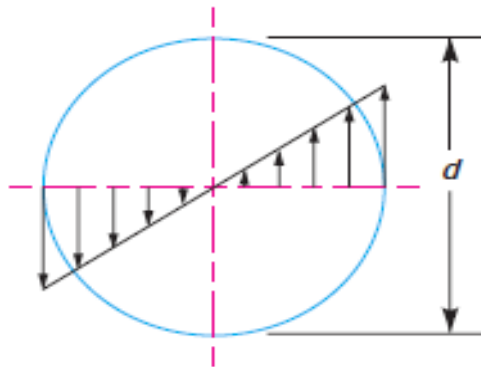
In addition to the torsional shear stress (τ_1) induced in the wire, the following stresses also act on the wire :

1. Direct shear stress due to the load W , and
2. Stress due to curvature of wire

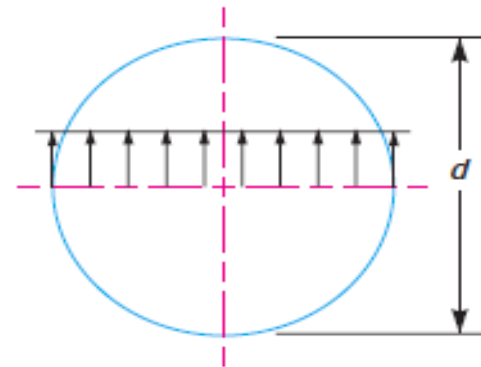
We know that direct shear stress due to the load W ,

$$\begin{aligned}\tau_2 &= \frac{\text{Load}}{\text{Cross-sectional area of the wire}} \\ &= \frac{W}{\frac{\pi}{4} \times d^2} = \frac{4W}{\pi d^2}\end{aligned}$$

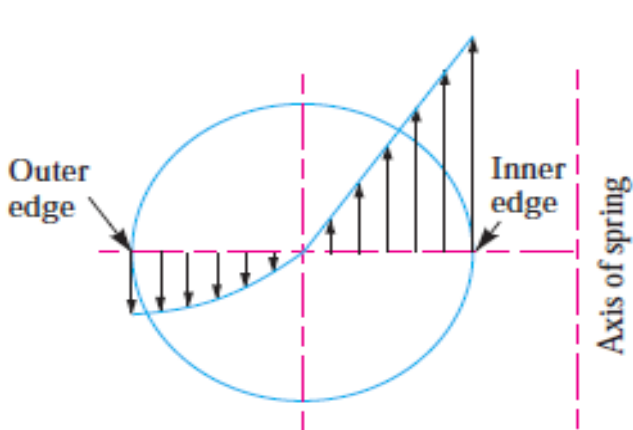
The direct shear stress diagram is shown in Fig. (b) and the resultant diagram of torsional shear stress and direct shear stress is shown in Fig (c)



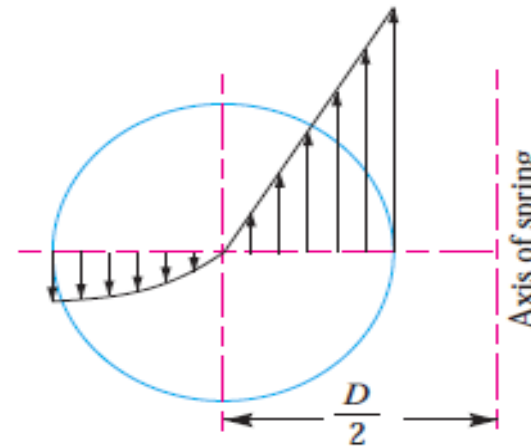
(a) Torsional shear stress diagram.



(b) Direct shear stress diagram.



(c) Resultant torsional shear and direct shear stress diagram.



(d) Resultant torsional shear, direct shear and curvature shear stress diagram.

We know that the resultant shear stress induced in the wire,

$$\tau = \tau_1 \pm \tau_2 = \frac{8W.D}{\pi d^3} \pm \frac{4W}{\pi d^2}$$

The *positive* sign is used for the inner edge of the wire and *negative* sign is used for the outer edge of the wire. Since the stress is maximum at the inner edge of the wire, therefore

Maximum shear stress induced in the wire,

= Torsional shear stress + Direct shear stress

$$= \frac{8W.D}{\pi d^3} + \frac{4W}{\pi d^2} = \frac{8W.D}{\pi d^3} \left(1 + \frac{d}{2D} \right)$$

$$= \frac{8 W.D}{\pi d^3} \left(1 + \frac{1}{2C} \right) = K_S \times \frac{8 W.D}{\pi d^3} \quad \dots(iii)$$

... (Substituting $D/d = C$)

where

$$K_S = \text{Shear stress factor} = 1 + \frac{1}{2C}$$

From the above equation, it can be observed that the effect of direct shear $\left(\frac{8 WD}{\pi d^3} \times \frac{1}{2C} \right)$ is appreciable for springs of small spring index C . Also we have neglected the effect of wire curvature in equation (iii). It may be noted that when the springs are subjected to static loads, the effect of wire curvature may be neglected, because yielding of the material will relieve the stresses.

In order to consider the effects of both direct shear as well as curvature of the wire, a Wahl's stress factor (K) introduced by A.M. Wahl may be used. The resultant diagram of torsional shear, direct shear and curvature shear stress is shown in Fig. 23.11 (d).

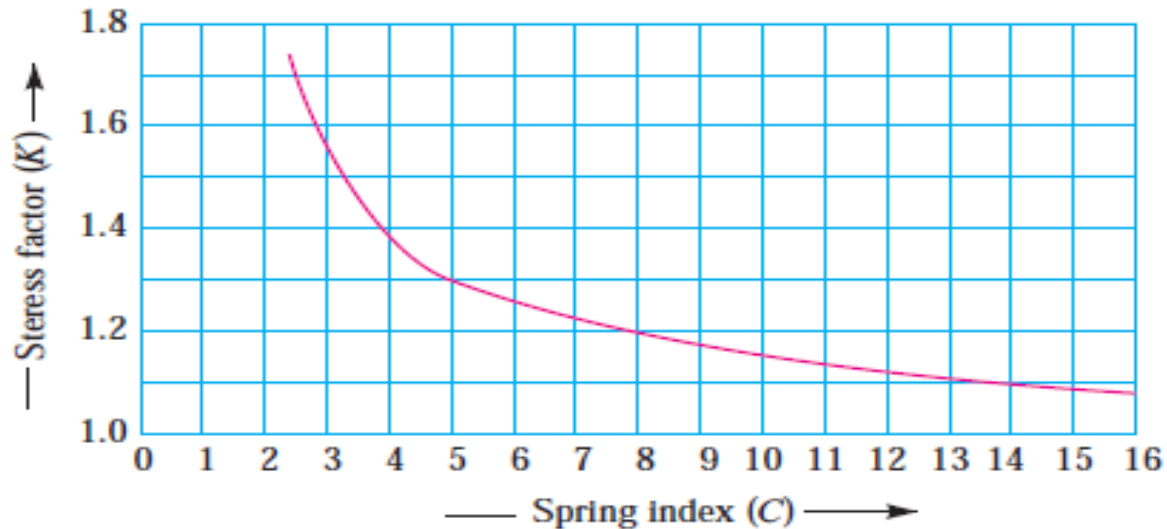
∴ Maximum shear stress induced in the wire,

$$\tau = K \times \frac{8 W.D}{\pi d^3} = K \times \frac{8 W.C}{\pi d^2} \quad \dots(iv)$$

where

$$K = \frac{4C - 1}{4C - 4} + \frac{0.615}{C}$$

The values of K for a given spring index (C) may be obtained from the graph as shown in Fig.



The Wahl's stress factor (K) may be considered as composed of two sub-factors, K_s and K_c , such that

$$K = K_s \times K_c$$

where K_s = Stress factor due to shear, and

K_c = Stress concentration factor due to curvature.