Design of Shafts on the basis of Rigidity

1. Torsional rigidity. The torsional rigidity is important in the case of camshaft of an I.C. engine where the timing of the valves would be effected. The permissible amount of twist should not exceed 0.25° per metre length of such shafts. For line shafts or transmission shafts, deflections 2.5 to 3 degree per metre length may be used as limiting value. The widely used deflection for the shafts is limited to 1 degree in a length equal to twenty times the diameter of the shaft.

The torsional deflection may be obtained by using the torsion equation,

$$\frac{T}{J} = \frac{G \cdot \theta}{L}$$
 or $\theta = \frac{T \cdot L}{J \cdot G}$

where

 θ = Torsional deflection or angle of twist in radians,

T =Twisting moment or torque on the shaft,

J =Polar moment of inertia of the cross-sectional area about the axis of rotation,

$$= \frac{\pi}{32} \times d^4 \qquad ... (For solid shaft)$$

$$\pi \left[(d)^4 (d)^4 \right]$$

$$= \frac{\pi}{32} \left[(d_o)^4 - (d_i)^4 \right] \qquad \dots \text{(For hollow shaft)}$$

G = Modulus of rigidity for the shaft material, and

L = Length of the shaft.

2. Lateral rigidity. It is important in case of transmission shafting and shafts running at high speed, where small lateral deflection would cause huge out-of-balance forces. The lateral rigidity is also important for maintaining proper bearing clearances and for correct gear teeth alignment. If the shaft is of uniform cross-section, then the lateral deflection of a shaft may be obtained by using the deflection formulae as in Strength of Materials. But when the shaft is of variable cross-section, then

the lateral deflection may be determined from the fundamental equation for the elastic curve of a beam, *i.e.*

$$\frac{d^2y}{dx^2} = \frac{M}{EI}$$