Shaft Subjected to Bending Moment Only

When the shaft is subjected to a bending moment only, then the maximum stress (tensile or compressive) is given by the bending equation. We know that

$$\frac{M}{I} = \frac{\sigma_b}{y} \qquad ...(i)$$

where

M =Bending moment,

I = Moment of inertia of cross-sectional area of the shaft about the axis of rotation,

 σ_{h} = Bending stress, and

y = Distance from neutral axis to the outer-most fibre.

We know that for a round solid shaft, moment of inertia,

$$I = \frac{\pi}{64} \times d^4 \quad \text{and} \quad y = \frac{d}{2}$$

Substituting these values in equation (i), we have

$$\frac{M}{\frac{\pi}{64} \times d^4} = \frac{\sigma_b}{\frac{d}{2}} \qquad \text{or} \qquad M = \frac{\pi}{32} \times \sigma_b \times d^3$$

From this equation, diameter of the solid shaft (d) may be obtained.

We also know that for a hollow shaft, moment of inertia,

$$I = \frac{\pi}{64} \left[(d_o)^4 - (d_i)^4 \right] = \frac{\pi}{64} (d_o)^4 (1 - k^4) \qquad \dots \text{(where } k = d_i / d_o)$$
$$y = d_o / 2$$

and

Again substituting these values in equation (i), we have

in substituting these values in equation (i), we have
$$\frac{M}{\frac{\pi}{64} (d_o)^4 (1-k^4)} = \frac{\sigma_b}{\frac{d_o}{2}} \quad \text{or} \quad M = \frac{\pi}{32} \times \sigma_b (d_o)^3 (1-k^4)$$

From this equation, the outside diameter of the shaft (d_i) may be obtained.

Shaft subjected to Combined Bending And Twisting Moment

When the shaft is subjected to combined twisting moment and bending moment, then the shaft must be designed on the basis of the two moments simultaneously. Various theories have been suggested to account for the elastic failure of the materials when they are subjected to various types of combined stresses. The following two theories are important from the subject point of view:

- Maximum shear stress theory or Guest's theory. It is used for ductile materials such as mild steel.
- Maximum normal stress theory or Rankine's theory. It is used for brittle materials such as cast iron.

Let

 τ = Shear stress induced due to twisting moment, and

σ_b = Bending stress (tensile or compressive) induced due to bending moment.

According to maximum shear stress theory, the maximum shear stress in the shaft,

$$\tau_{max} = \frac{1}{2} \sqrt{(\sigma_b)^2 + 4\tau^2}$$

$$\tau_{max} = \frac{1}{2} \sqrt{\left(\frac{32M}{\pi d^3}\right)^2 + 4\left(\frac{16T}{\pi d^3}\right)^2} = \frac{16}{\pi d^3} \left[\sqrt{M^2 + T^2}\right]$$

$$\frac{\pi}{16} \times \tau_{max} \times d^3 = \sqrt{M^2 + T^2} \qquad ...(i)$$

or

The expression $\sqrt{M^2 + T^2}$ is known as *equivalent twisting moment* and is denoted by T_e . The equivalent twisting moment may be defined as that twisting moment, which when acting alone, produces the same shear stress (τ) as the actual twisting moment. By limiting the maximum shear stress (τ) equal to the allowable shear stress (τ) for the material, the equation (i) may be written as

$$T_e = \sqrt{M^2 + T^2} = \frac{\pi}{16} \times \tau \times d^3 \qquad \dots (ii)$$

From this expression, diameter of the shaft (d) may be evaluated.

Now according to maximum normal stress theory, the maximum normal stress in the shaft,

$$\sigma_{b(max)} = \frac{1}{2} \sigma_b + \frac{1}{2} \sqrt{(\sigma_b)^2 + 4\tau^2} \qquad ...(iii)$$

$$= \frac{1}{2} \times \frac{32M}{\pi d^3} + \frac{1}{2} \sqrt{\left(\frac{32M}{\pi d^3}\right)^2 + 4\left(\frac{16T}{\pi d^3}\right)^2}$$

$$= \frac{32}{\pi d^3} \left[\frac{1}{2} (M + \sqrt{M^2 + T^2}) \right]$$

or

$$\frac{\pi}{32} \times \sigma_{b \, (max)} \times d^3 = \frac{1}{2} \left[M + \sqrt{M^2 + T^2} \right]$$
 ...(iv)

The expression $\frac{1}{2} \left[(M + \sqrt{M^2 + T^2}) \right]$ is known as equivalent bending moment and is denoted by M_c . The equivalent bending moment may be defined as that moment which when acting alone produces the same tensile or compressive stress (σ_b) as the actual bending moment. By limiting the maximum normal stress $[\sigma_{b(max)}]$ equal to the allowable bending stress (σ_b) , then the equation (iv) may be written as

$$M_e = \frac{1}{2} \left[M + \sqrt{M^2 + T^2} \right] = \frac{\pi}{32} \times \sigma_b \times d^3$$
 ...(v)

From this expression, diameter of the shaft (d) may be evaluated.

Notes: 1. In case of a hollow shaft, the equations (ii) and (v) may be written as

$$T_e = \sqrt{M^2 + T^2} = \frac{\pi}{16} \times \tau (d_o)^3 (1 - k^4)$$

$$M_e = \frac{1}{2} \left(M + \sqrt{M^2 + T^2} \right) = \frac{\pi}{32} \times \sigma_b (d_o)^3 (1 - k^4)$$