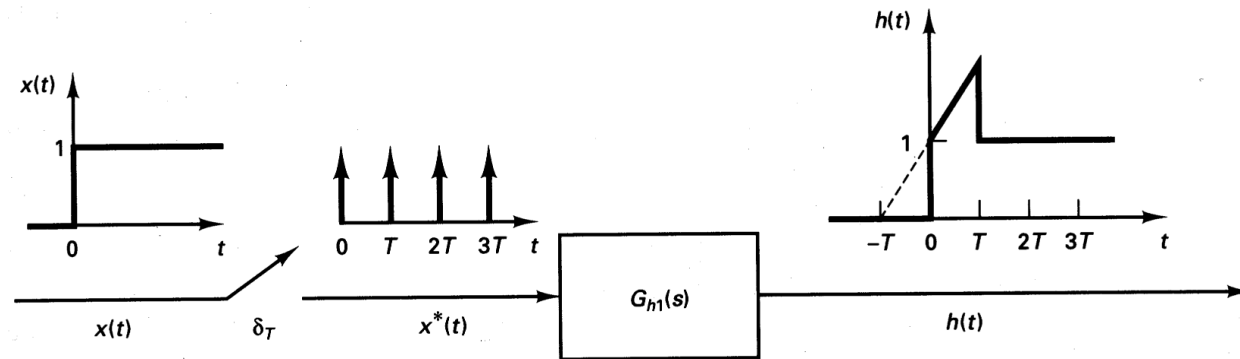


Impulse Sampling and Data Hold

- Transfer function of First-Order Hold (cont.)
 - Derivation of the transfer function (cont.)



$$X^*(s) = \sum_{k=0}^{\infty} 1(kT)e^{-kTs} = \frac{1}{1-e^{-Ts}}$$

The transfer function

$$G_{h1}(s) = \frac{H(s)}{X^*(s)} = \left(1 - e^{-Ts}\right)^2 \frac{Ts + 1}{Ts^2} = \left(\frac{1 - e^{-Ts}}{s}\right)^2 \frac{Ts + 1}{T}$$

Reconstructing Original Signals from Sampled Signals

$$X^* s(x) \Big|_{s=\frac{1}{T}\ln Z} \sum_{K=0}^{\infty} X(KT)Z^{-K} = X(Z)$$

$$x^*(t) = x(t) \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$$\delta_T(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT) = \sum_{n=-\infty}^{\infty} C_n e^{jnW_s t}$$

$$C_n = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} \delta_T(t) e^{-jnW_s t} dt = \frac{1}{T} e^{-j0} = \frac{1}{T}$$

$$\delta_T(t) = \frac{1}{T} \sum_{n=-\infty}^{\infty} e^{jnW_s t}$$

$$X^*(s) = \frac{1}{T} x(t) \sum_{n=-\infty}^{\infty} e^{jnW_s t}$$

Reconstructing Original Signals from Sampled Signals

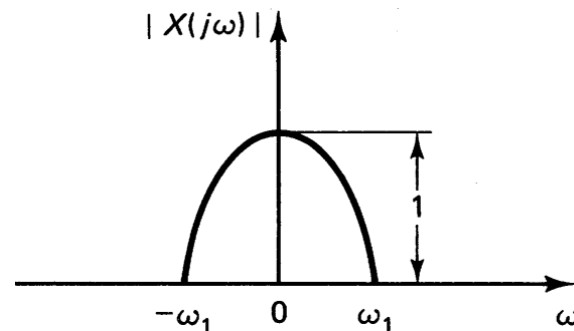
$$\begin{aligned} X^*(s) &= \frac{1}{T} \int_0^{\infty} x(t) \sum_{n=-\infty}^{\infty} e^{jnW_s t} e^{-st} dt \\ &= \frac{1}{T} \sum_{n=-\infty}^{\infty} \int_0^{\infty} x(t) e^{-(S-jnW_s)t} dt \end{aligned}$$

$$X^*(s) = \frac{1}{T} \sum_{n=-\infty}^{\infty} X(S - jnW_s)$$

Reconstructing Original Signals from Sampled Signals

- Sampling Theorem

- If the sampling frequency is sufficiently high compared with the highest-frequency component involved in the continuous-time signal, the amplitude characteristics of the continuous-time signal may be preserved in the envelope of the sampled signal.
- To reconstruct the original signal from a sampled signal, there is a certain minimum frequency that the sampling operation must satisfy.
- We assume that $x(t)$ does not contain any frequency components above ω_1 rad/sec.



Reconstructing Original Signals from Sampled Signals

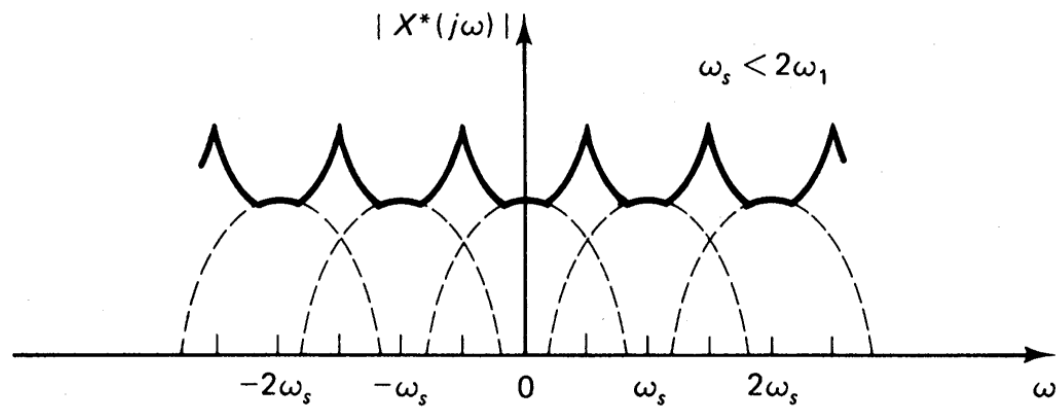
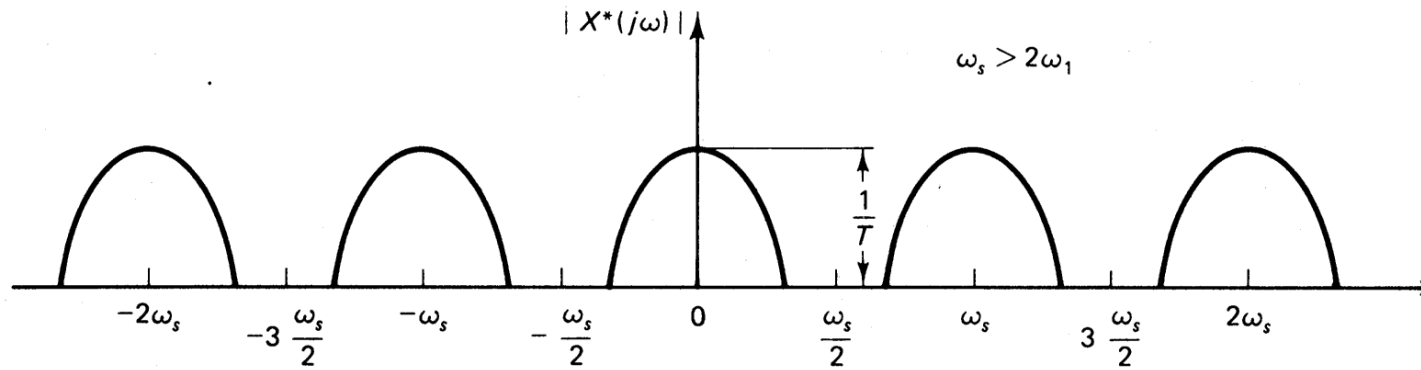
- Sampling Theorem

If ω_s , defined as $2\pi/T$ is greater than $2\omega_1$, where ω_1 is the highest-frequency component present in the continuous-time signal $x(t)$, then the signal $x(t)$ can be reconstructed completely from the sampled signal $x^*(t)$.

– The frequency spectrum:

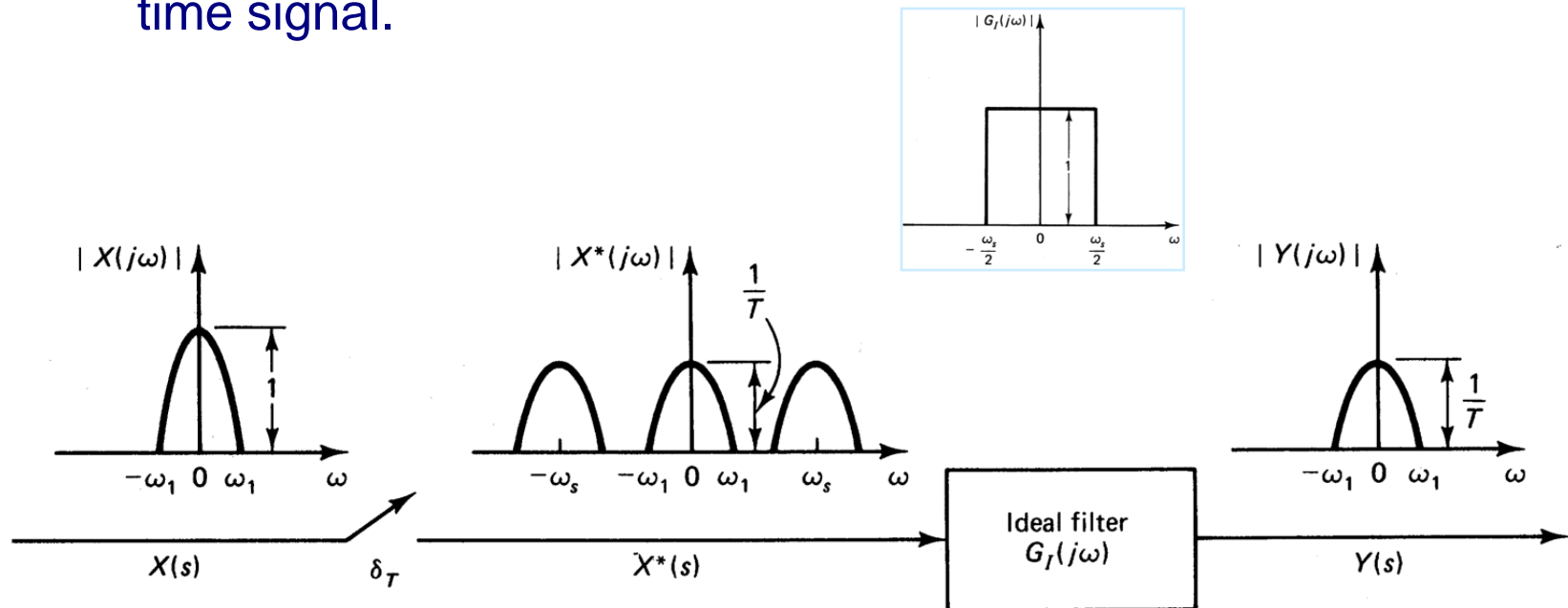
$$\begin{aligned} X^*(j\omega) &= \frac{1}{T} \sum_{k=-\infty}^{k=\infty} X(j\omega + j\omega_s k) \\ &= \dots + \frac{1}{T} X(j(\omega - \omega_s)) + \frac{1}{T} X(j\omega) + \frac{1}{T} X(j(\omega + \omega_s)) + \dots \end{aligned}$$

Reconstructing Original Signals from Sampled Signals



Reconstructing Original Signals from Sampled Signals

- Ideal Low-pass filter
 - The ideal filter attenuates all complementary components to zero and will pass only the primary component.
 - If the sampling frequency is less than twice the highest-frequency component of the original continuous-time signal, even the ideal filter cannot reconstruct the original continuous-time signal.

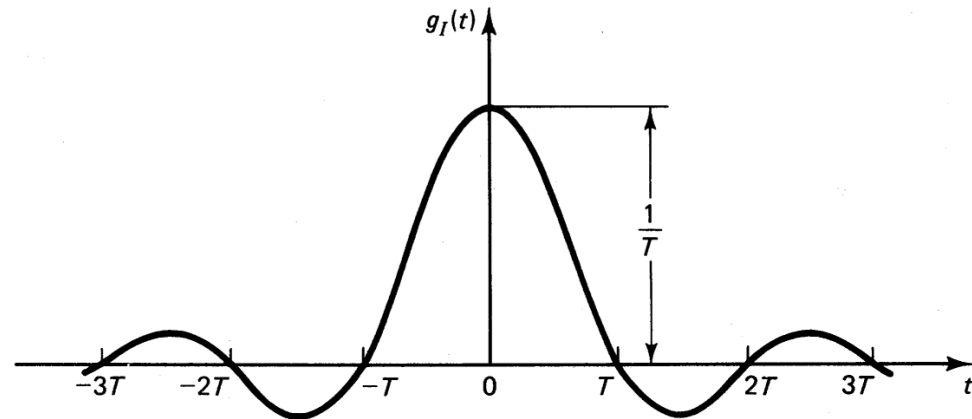


Reconstructing Original Signals from Sampled Signals

- Ideal Low-pass filter Is NOT Physically Realizable
 - For the ideal filter an output is required prior to the application of the input to the filter – *physically not realizable*.

$$G_I(j\omega) = \begin{cases} 1, & -\frac{1}{2}\omega_s \leq \omega \leq \frac{1}{2}\omega_s \\ 0, & \text{elsewhere} \end{cases}$$

$$\begin{aligned} g_I(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} G_I(j\omega) e^{j\omega t} d\omega \\ &= \frac{1}{2\pi} \int_{-\omega_s/2}^{\omega_s/2} e^{j\omega t} d\omega \\ &= \frac{1}{2\pi jt} \left(e^{(1/2)j\omega_s t} - e^{-(1/2)j\omega_s t} \right) \\ &= \frac{1}{\pi t} \sin \frac{\omega_s t}{2} \\ &= \frac{1}{T} \frac{\sin(\omega_s t / 2)}{\omega_s t / 2} \end{aligned}$$



Reconstructing Original Signals from Sampled Signals

- Frequency-Response Characteristics of the ZOH

Transfer function of ZOH $G_{h0}(s) = \frac{1 - e^{-Ts}}{s}$

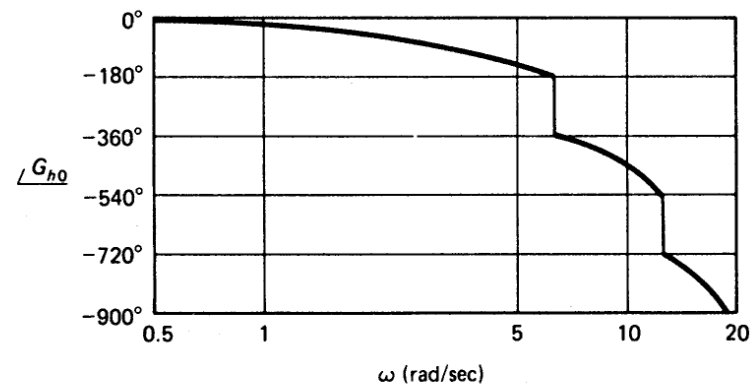
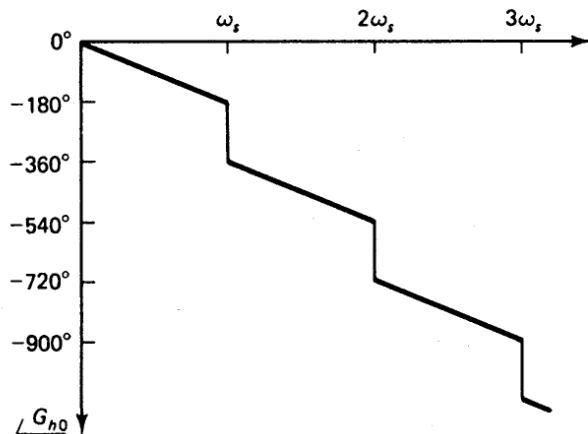
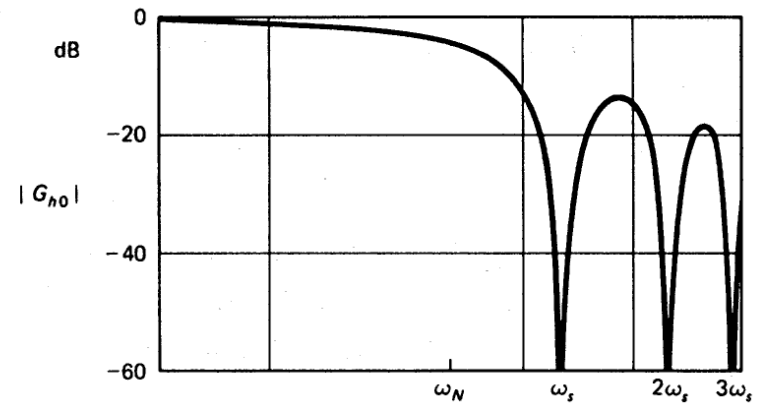
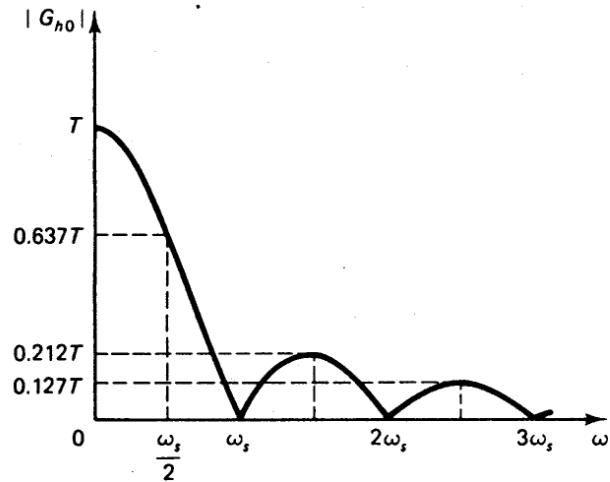
$$\begin{aligned} G_{h0}(j\omega) &= \frac{1 - e^{-Tj\omega}}{j\omega} \\ &= \frac{2e^{-(1/2)Tj\omega} (e^{(1/2)Tj\omega} - e^{-(1/2)Tj\omega})}{2j\omega} \\ &= T \frac{\sin(\omega T / 2)}{\omega T / 2} e^{-(1/2)Tj\omega} \end{aligned}$$

$$|G_{h0}(j\omega)| = T \left| \frac{\sin(\omega T / 2)}{\omega T / 2} \right|$$

$$\begin{aligned} \angle G_{h0}(j\omega) &= \angle T \frac{\sin(\omega T / 2)}{\omega T / 2} e^{-(1/2)Tj\omega} \\ &= \angle \sin \frac{\omega T}{2} + \angle e^{-(1/2)Tj\omega} \\ &= \angle \sin \frac{\omega T}{2} - \frac{\omega T}{2} \end{aligned}$$

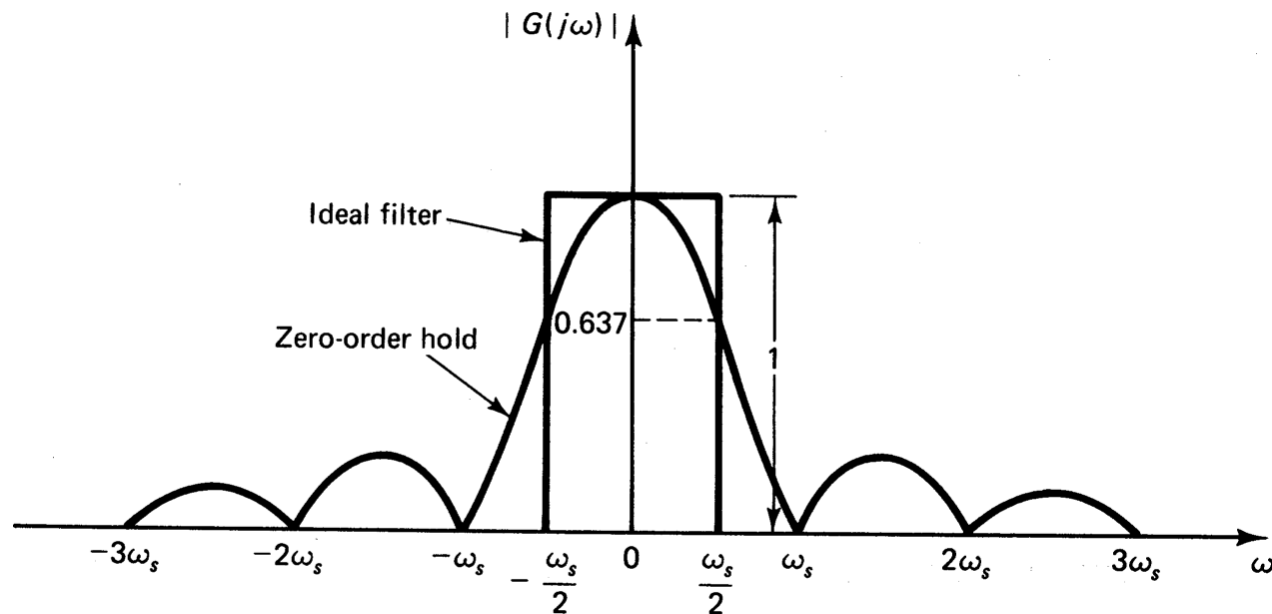
Reconstructing Original Signals from Sampled Signals

- Frequency-Response Characteristics of the ZOH(cont.)



Reconstructing Original Signals from Sampled Signals

- Frequency-Response Characteristics of the ZOH(cont.)
 - The comparison of the ideal filter and the ZOH.
 - ZOH is a low-pass filter, although its function is not quite good.
 - The accuracy of the ZOH as an extrapolator depends on the sampling frequency.



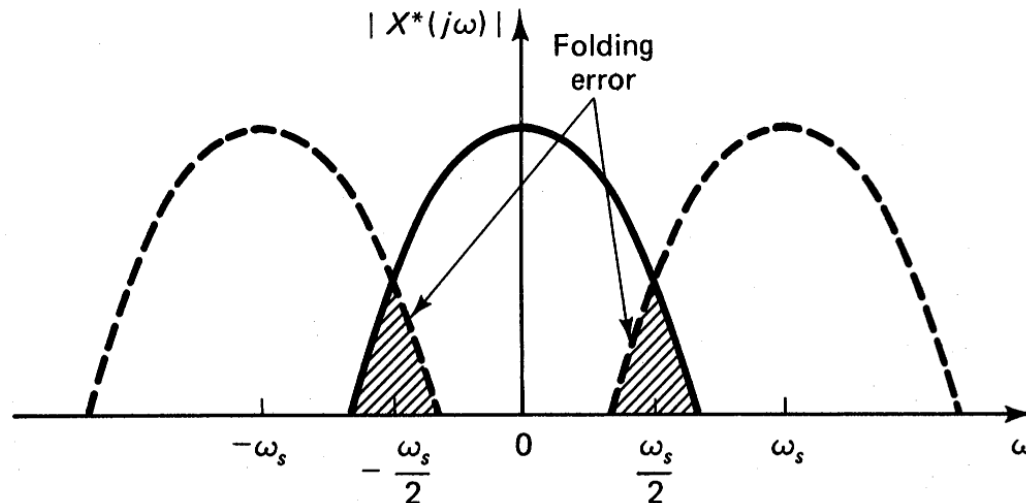
Reconstructing Original Signals from Sampled Signals

- Folding

- The phenomenon of the overlap in the frequency spectra.
- The folding frequency (Nyquist frequency): ω_N

$$\omega_N = \frac{1}{2} \omega_s = \frac{\pi}{T}$$

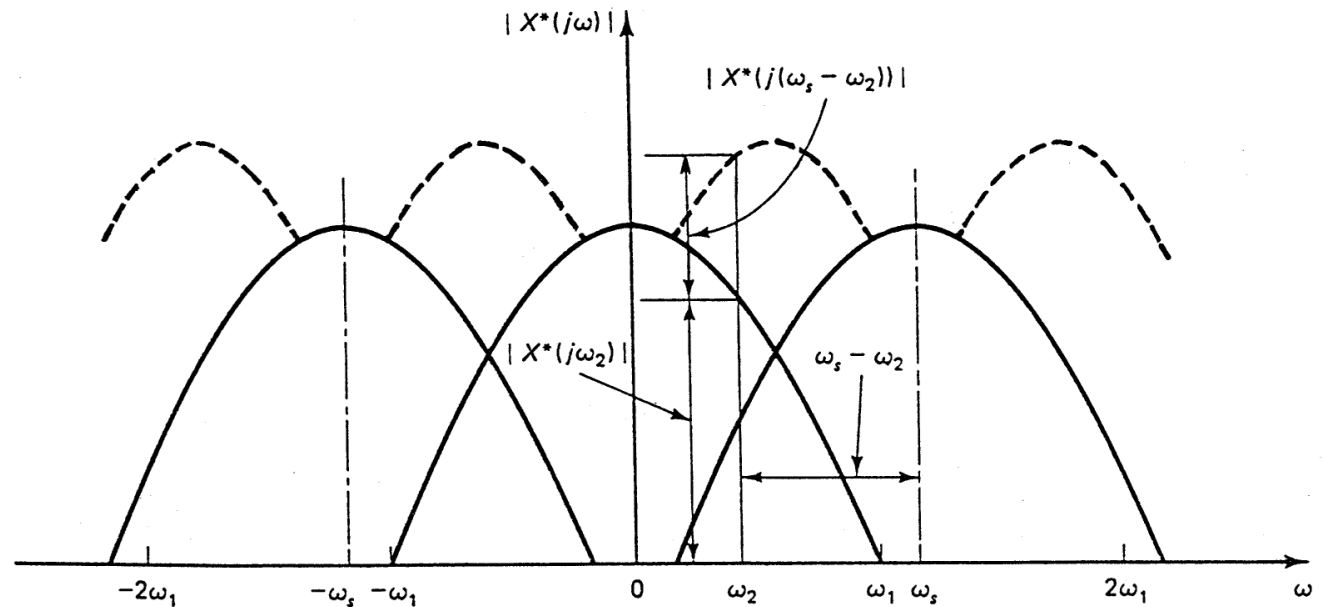
- In practice, signals in control systems have high-frequency components, and some **folding effect** will almost always exist.



Reconstructing Original Signals from Sampled Signals

- Aliasing

- The phenomenon that the frequency component $n\omega_s \pm \omega_2$ shows up at frequency ω_2 when the signal $x(t)$ is sampled.
- To avoid aliasing, we must either choose the sampling frequency high enough or use a prefilter ahead of the sampler to reshape the frequency spectrum of the signal before the signal is sampled.



Reconstructing Original Signals from Sampled Signals

- Hidden Oscillation
 - An oscillation existing in $x(t)$ between the sampling periods.

For example, if the signal

$$x(t) = x_1(t) + x_2(t) = \sin t + \sin 3t$$

is sampled at $t=0, 2\pi/3, 4\pi/3, \dots$, then the sampled signal will not show the frequency component with $\omega=3$ rad/sec.

