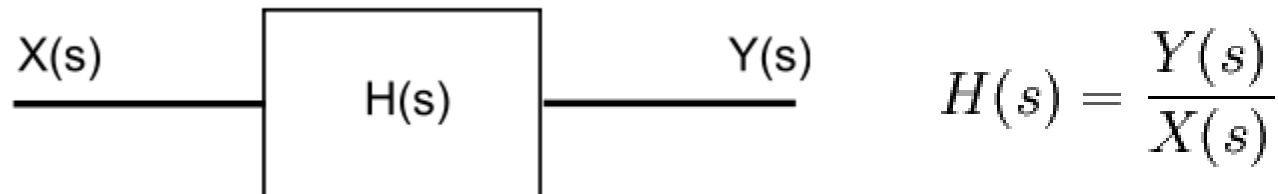


Chapter:2

Mathematical Modelling

Definition of Transfer Function

- Transfer Function reveals how the circuit modifies the input amplitude in creating output amplitude.
- Therefore, transfer function describes how the circuit processes the input to produce output.



Transfer Function is the ratio of the output of a system to the input of a system, in the Laplace domain considering its initial conditions to be zero.

Frequency Domain

Resistor

$$V(s) = RI(s)$$

$$V = RI$$



Inductor

$$V(s) = sLI(s)$$

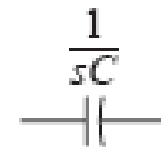
$$V = sLI$$



Capacitor

$$V(s) = \frac{1}{sC}I(s)$$

$$V = \frac{1}{sC}I$$



$$v_R(t) = Ri(t) \quad V_R(s) = RI(s)$$

$$v_L(t) = L \frac{di}{dt} \quad V_L(s) = sLI(s)$$

$$v_C(t) = \frac{1}{C} \int idt \quad V_C(s) = \frac{1}{sC} I(s)$$

Time constants:

$$T_{RC} = RC = \frac{V}{A} \frac{Q}{V} = \frac{VQ}{\frac{Q}{\text{sec}} V} = \text{sec}$$

$$T_{RL} = \frac{L}{R} = \frac{\frac{V}{A}}{\frac{\text{sec}}{V}} = \text{sec}$$

Frequency Domain

Resistor

$$V(s) = RI(s)$$

$$V = RI$$



Inductor

$$V(s) = sLI(s)$$

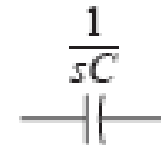
$$V = sLI$$



Capacitor

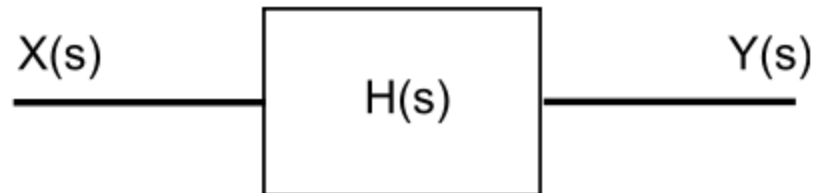
$$V(s) = \frac{1}{sC}I(s)$$

$$V = \frac{1}{sC}I$$



Definition of Transfer Function

Transfer Function is the ratio of the output of a system to the input of a system, in the Laplace domain considering its initial conditions to be zero.



$$H(s) = \frac{Y(s)}{X(s)}$$

Frequency Domain

Resistor

$$V(s) = RI(s)$$

$$V = RI$$



Inductor

$$V(s) = sLI(s)$$

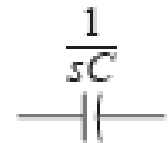
$$V = sLI$$



Capacitor

$$V(s) = \frac{1}{sC}I(s)$$

$$V = \frac{1}{sC}I$$

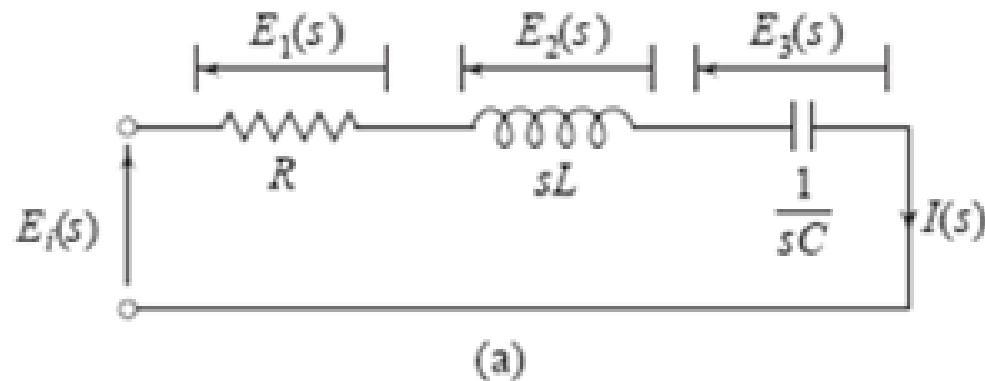


$$\frac{V(s)}{I(s)} = R$$

$$\frac{V(s)}{I(s)} = sL$$

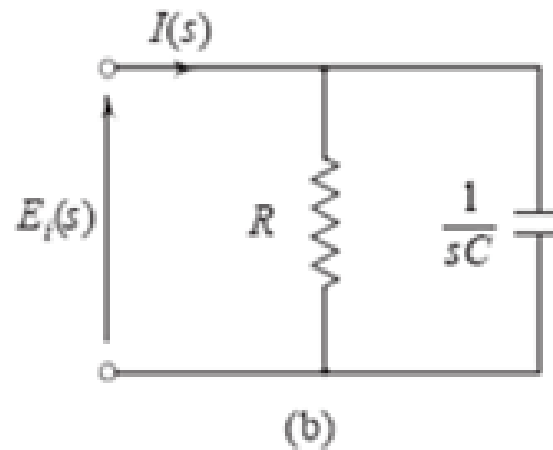
$$\frac{V(s)}{I(s)} = \frac{1}{sC}$$

Impedances in series



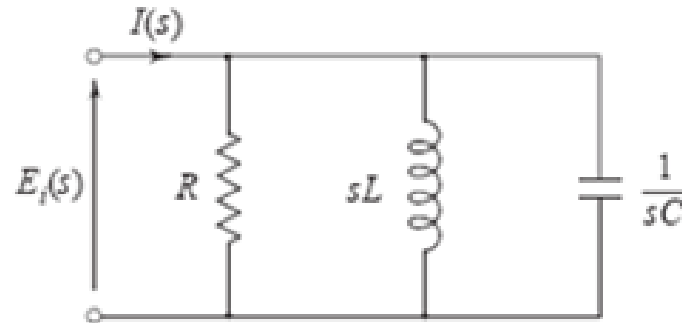
$$\mathbf{Z (s)}_{eq} = \frac{\mathbf{E_i (s)}}{\mathbf{I (s)}} = \mathbf{R + \frac{1}{sC} + Ls}$$

Impedances in parallel



$$Z(s)_{\text{eq}} = \frac{E_i(s)}{I(s)} = \frac{R}{C \left(R + \frac{1}{Cs} \right) s}$$

Impedance Approach



(c)

$$\frac{1}{Z(s)_{\text{eq}}} = Y(s)_{\text{eq}} = \frac{I(s)}{E_i(s)} = \frac{1}{R} + Cs + \frac{1}{Ls} \quad \text{or}$$

$$Z(s)_{\text{eq}} = \frac{E_i(s)}{I(s)} = \frac{LR}{C\left(R + \frac{1}{Cs}\right) \left(\frac{R}{C\left(R + \frac{1}{Cs}\right)s} + Ls\right)}$$

Derivation of Transfer Function

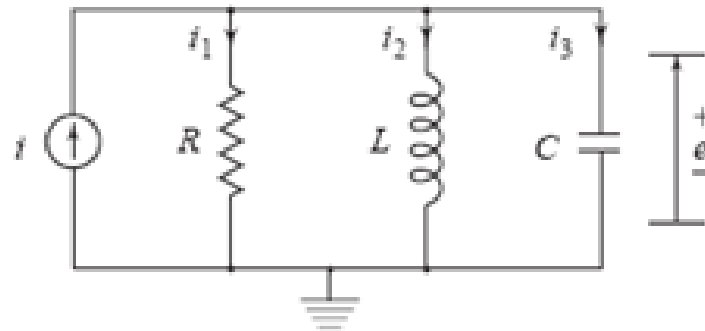
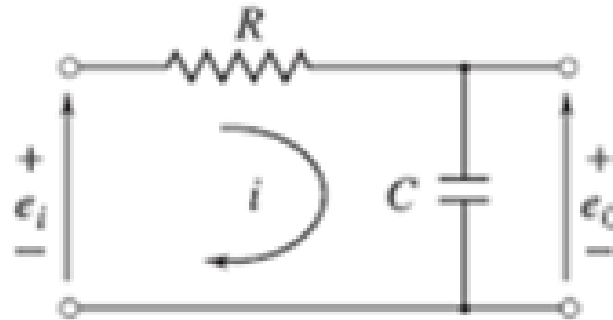


Fig. 2.28 An RLC circuit

$$H(s) = \frac{\frac{L}{C \left(\frac{1}{Cs} + Ls \right)}}{R + \frac{L}{C \left(\frac{1}{Cs} + Ls \right)}}$$

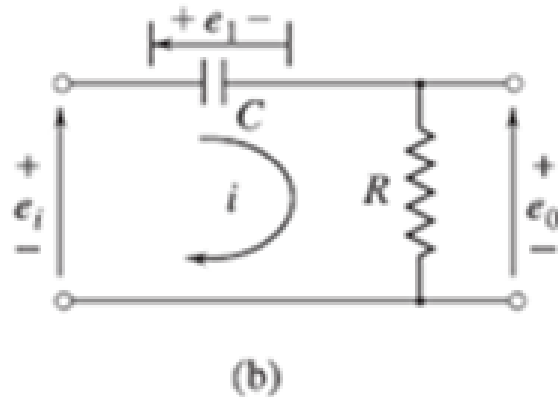
Derivation of Transfer Function



(a)

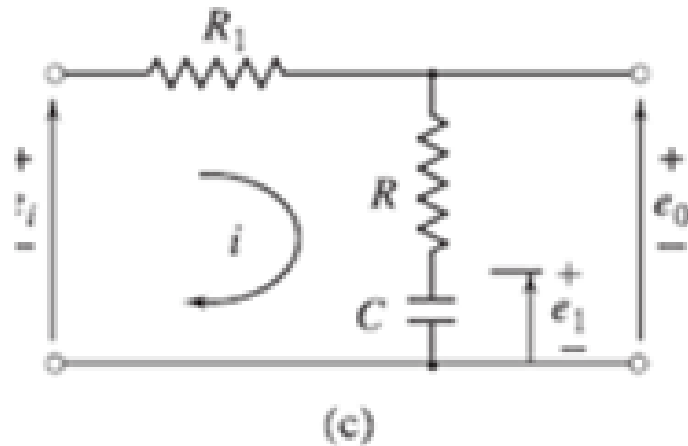
$$H(s) = \frac{1}{C \left(R + \frac{1}{Cs} \right) s}$$

Derivation of Transfer Function



$$H(s) = \frac{R}{R + \frac{1}{Cs}}$$

Derivation of Transfer Function



$$H(s) = \frac{R + \frac{1}{Cs}}{R + R_1 + \frac{1}{Cs}}$$

- Define transfer function. derive transfer function of an armature controlled D. C motor