## Linear Programming Models

"Programming" here means "Planning"



LP Modeling

## Graphical iepresentainon



In two dimensions, the graph of a linear equation is a line, and the graph of a linear inequality is a half-space
(including the line).
To draw the graph of a linear inequality, first
draw the graph of the equation, and then decide which side is the correct half-space by testing whether $(0,0)$ is feasible.

In three dimensions, the graph of a linear equation is a plane.
In $\boldsymbol{n}$ dimensions, the graph of a linear equation is a hyperplane.

## Exercise



Graph the linear inequality:
$X_{1}-X_{2} \leq 2$
(Shade the region representing points
which are feasible in both inequalities.)
(exercise, continued)


Graph the solutions of the pair of
linear inequalities:
$\left\{\begin{array}{l}X_{1}-X_{2} \leq 2 \\ X_{1}+3 X_{2} \geq 6\end{array}\right.$
(Shade the region representing points which are feasible in both inequalities.)
linear programming (LP): an optimization problem for which

- we maximize or minimize a linear function of the decision variables (this function is called the objective function)
- the values of the decision variables must satisfy a set of constraints, each consisting of a linear equation or linear inequality
- a sign restriction, i.e., usually nonnegativity $\left(x_{i} \geq 0\right)$ but perhaps nonpositivity $\left(x_{i} \leq 0\right)$, may be associated with each decision variable.

```
example:
            maximize 2x}+\mp@subsup{x}{2}{
            subject to }3\mp@subsup{x}{1}{}-\mp@subsup{x}{2}{}\geq
\[
\begin{array}{r}
2 x_{1}+3 x_{2} \leq 12 \\
x_{1} \geq 0, x_{2} \geq 0
\end{array}
\]
```


## Graphical Representation

maximize $2 x_{1}+x_{2}$
subject to $3 x_{1}-x_{2} \geq 6$

$$
\begin{array}{r}
2 x_{1}+3 x_{2} \leq 12 \\
x_{1} \geq 0, x_{2} \geq 0
\end{array}
$$



Each point in the shaded feasible region satisfies all four inequality constraints (including nonnegativity) and represents a possible solution of the problem.

The optimal solution is the feasible solution for which the objective function is largest.

By graphing the linear equations

$$
2 X_{1}+X_{2}=0,2 X_{1}+X_{2}=4,2 X_{1}+X_{2}=12, \text { etc. }
$$

we see that the slope remains the same,
 but the line is shifted to the right.

How far to the right can the line be shifted while still including a feasible solution of the set of inequalities?

The optimal solution is the corner farthest to the right, $\left(X_{1}, X_{2}\right)=(6,0)$.

In fact, an optimal solution of an LP problem can always be found at a corner point!

## Example:

- A manufacturer can make two products: P and Q.
- Each product requires processing time on each of four machines: A, B, C, and D.
- Each machine is available 24 hours per day $=1440$ minutes per day.
- The profit per unit of products $P$ and Q are $\$ 45$ and $\$ 60$, respectively.
- Maximum demand for products P and Q are 100/day and 40/day, respectively.

|  | Unit Processing | Time (minutes) |  |
| :---: | :---: | :---: | :---: |
| Machine $\backslash$ Product: | P | Q | Available (min.) |
| A | 20 | 10 | 1440 |
| B | 12 | 28 | 1440 |
| C | 15 | 6 | 1440 |
| D | 10 | 15 | 1440 |
| Profit/unit | 45 | 60 |  |

How much of each product should be manufactured each day in order to maximize profits?

Define the decision variables
$\mathrm{P}=$ number of units/day of product $P$
$\mathrm{Q}=$ number of units/day of product $Q$
Objective: Maximize $45 P+60 Q$ (\$/day)
Constraints: do not exceed the available processing time on each machine:

$$
\begin{aligned}
20 P+10 Q & \leq 1440 \\
12 P+28 Q & \leq 1440 \\
15 P+6 Q & \leq 1440 \\
10 P+15 Q & \leq 1440
\end{aligned}
$$

do not produce more than the demand for the products:

$$
P \leq 100
$$

$$
Q \leq 40
$$

a negative quantity of product is meaningless:

$$
P \geq 0, Q \geq 0
$$



The maximum profit is obtained at the corner point $(P, Q)=(58.9,26.2)$

Note: I clearly erred in drawing the isoquant line for the profit!

The graphical method for solving an LP problem is useless for problems with more than 2 (possibly 3 ) decision variables...

## Problems occurring in "the real world" may involve

a million decision variables and
thousands of constraints!

We will study computational methods for solving linear programming problems.

LINGO Model－LINGO1
Ready

$$
\begin{aligned}
& \text { Max= 4.5 } \mathrm{F}+6 \mathrm{O} \text { \# } \mathrm{Z} \\
& 2 口 * P+1 口 * Q<1440 ; \\
& 12 * \mathrm{P}+2 \mathrm{~B} * \mathrm{Q}<144 \mathrm{O} \text {; } \\
& 15 * P+6 * Q<=1440 \text {; }
\end{aligned}
$$

$$
\begin{aligned}
& \text { P<=100; } \\
& \text { Q< }=40 \text { : }
\end{aligned}
$$

LINGO is a software package for solving LP problems．．．．
（by default， variables are assumed to be nonnegative．）

## SOLUTION:

| Global optimal solution Objective value: | ep: $4221.8$ |  |
| :---: | :---: | :---: |
|  | Value | Reduced Cost |
|  | 58.90909 | 0.0000000 |
|  | 26.18182 | 0.0000000 |
|  | Slack or Surplus | Dual Price |
|  | 4221.818 | 1.000000 |
|  | 0.0000000 | 1.227273 |
|  | 0.0000000 | 1.704545 |
|  | 399.2727 | 0.0000000 |
|  | 458.1818 | 0.0000000 |
|  | 41.09091 | 0.0000000 |
|  | 13.81818 | 0.0000000 |

LP Modeling

That is, the manufacturer will maximize profits by producing 58.9 units of P and 26.18 units of Q each day (assuming fractional units are possible).

This plan will yield a profit of \$4221.818/day.

| Row | Slack or Surplus | Dual Price |
| ---: | :---: | :---: |
| 1 | 4221.818 | 1.000000 |
| 2 | 0.0000000 | 1.227273 |
| 3 | 0.0000000 | 1.704545 |
| 4 | 399.2727 | 0.0000000 |
|  | 5 | 458.1818 |
| 6 | 41.09091 | 0.0000000 |
|  | 7 | 13.81818 |

This plan will use all of the available time on machines A and B, i.e.,

$$
S_{A}=S_{B}=0
$$

but unused time on machines C \& D will be 399.27 and 458.18, respectively,
that is, $S_{C}=399.2727$ and $S_{D}=458.1818$.

## Computational Methods for Solving LPs

It is more convenient to work with linear equations rather than linear inequalities.

Define "slack" variables $S_{A}, S_{B}, S_{C} \& S_{D}$ to be the unused processing time on machines $\mathrm{A}, \mathrm{B}, \mathrm{C} \& \mathrm{D}$, respectively.

Then, for example, the inequality constraint for machine A is equivalent to the linear equation and nonnegativity restriction:

$$
20 P+10 Q \leq 1440 \quad \Leftrightarrow \quad 20 P+10 Q+S_{A}=1440 \& S_{A} \geq 0
$$

Thus we obtain the system of equations (\& simple bounds on the variables):

$$
\left\{\begin{array} { r } 
{ 2 0 P + 1 0 Q \leq 1 4 4 0 } \\
{ 1 2 P + 2 8 Q \leq 1 4 4 0 } \\
{ 1 5 P + 6 Q \leq 1 4 4 0 } \\
{ 1 0 P + 1 5 Q \leq 1 4 4 0 }
\end{array} \Leftrightarrow \left\{\begin{array}{ll}
20 P+10 Q+S_{A} & =1440 \\
12 P+28 Q+S_{B} & =1440 \\
15 P+6 Q \quad+S_{C}=1440 \\
10 P+15 Q \quad+S_{D}=1440 \\
0 \leq P \leq 100,0 \leq Q \leq 40, \\
S_{A} \geq 0, S_{B} \geq 0, S_{C} \geq 0, S_{D} \geq 0
\end{array}\right.\right.
$$

Next we will review computational methods for solving systems of linear equations!

