

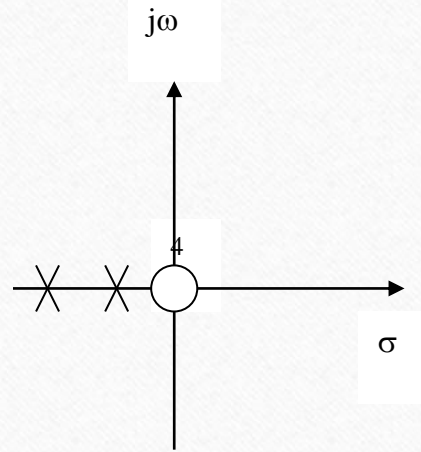
# Region of Convergence (ROC)

# Region of Convergence (ROC) for Laplace Transform

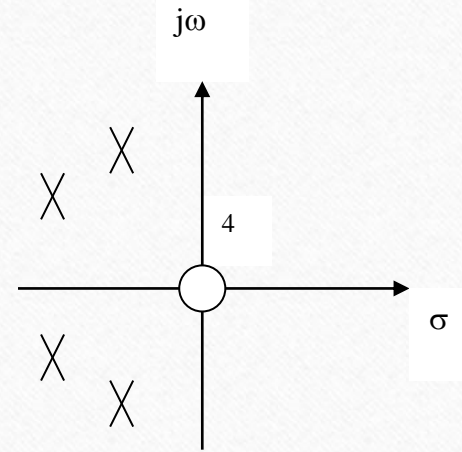
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- The  $s$ -plane refers to the domain where all the possible values of  $H(s)$  occur.
- If the polynomial order is 2 with real poles and zeros, the positions of the poles and zeros in the  $s$ -plane is shown Figure 1(a).
- Similar example for complex poles and zeroes are shown in Figure 1(b).
- For causal systems, the system is stable if the poles are on the right hand side of the  $s$ -plane.

# ROC



1(a) Real poles and zeros.



2(b) Complex poles and zeros.

# Differential Solution and Transfer Function

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- Many physical phenomena can be defined as differential equation

$$\frac{d^2}{dt^2} y(t) + a(1) \frac{d}{dt} y(t) + a(2) y(t) = x(t)$$

where  $y(t)$  is the output and  $x(t)$  is the input. The Laplace transform is one way of solving the relationship between  $y(t)$  and  $x(t)$ .

$$s^2 Y(s) + a(1) s Y(s) + a(2) Y(s) = X(s)$$

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- The transfer function of the system obtained by taking the ratio of  $Y(s)$  and  $X(s)$  is:

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 + a(1)s + a(2)}$$

- For a more general case, the transfer function is in the form of:

$$H(s) = \frac{b(0)s^N + b(1)s^{N-1} + b(2)s^{N-2} + \dots + b(N)}{s^N + a(1)s^{N-1} + a(2)s^{N-2} + \dots + a(N)} = \frac{\sum_{n=0}^N b(n)s^{(N-n)}}{\sum_{n=0}^N a(n)s^{(N-n)}}$$

where  $N$  is the polynomial order. The transfer function when factorized in terms of its roots is:

$$H(s) = \frac{(s + \beta(0))(s + \beta(1))\dots(s + \beta(N))}{(s + \alpha(0))(s + \alpha(1))\dots(s + \alpha(N))} = \frac{\prod_{n=0}^N (s + \beta(n))}{\prod_{n=0}^N (s + \alpha(n))}$$

- The roots in the numerator  $-\beta(0), -\beta(1) \dots -\beta(N)$  are referred as the zeros while the roots in the denominator  $-\alpha(0), -\alpha(1) \dots -\alpha(N)$  are the poles.

# Inverse Laplace Transform

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- Definition:

$$x(t) = \frac{1}{2\pi j} \int_{\sigma - j\infty}^{\sigma + j\infty} X(s)e^{st} ds = \frac{1}{2\pi j} \int_{\sigma - j\omega}^{\sigma + j\omega} X(s)e^{st} ds$$

- $s$  is a complex variable that is defined as  $s = \sigma + j\omega$ .
- $\sigma$  fixed and  $\omega$  varying from  $-\infty$  to  $\infty$ .
- we usually use table of Laplace transform pairs to perform Inverse Laplace Transform.

• Example 4

- Compute  $x(t)$  if  $X(s) = 3/s^2$

$$\begin{aligned}x(t) &= L^{-1}[X(s)] = L^{-1}\left[\frac{3}{s^2}\right] \\ &= 3L^{-1}\left[\frac{1}{s^2}\right] = 3t\end{aligned}$$

- Compute  $f(t)$  if  $F(s) = \frac{2s}{s^2 + 10}$

$$f(t) = 2 \cos \sqrt{10}t$$



- By taking the inverse Laplace transform, the system impulse response  $h(t)$  is obtained from  $H(s)$ .

- If the following transfer function is used as example:

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 + a(1)s + a(2)} = \frac{1}{(s + \alpha(0))(s + \alpha(1))}$$

- The application of the partial fraction expansion results in:

$$H(s) = \frac{1}{(s + \alpha(0))(s + \alpha(1))} = \frac{A_0}{(s + \alpha(0))} + \frac{A_1}{(s + \alpha(1))}$$

- From Laplace Transform pairs, the system impulse response,  $h(t)$  is:

$$h(t) = A_0 e^{-\alpha(0)t} + A_1 e^{-\alpha(1)t}$$

- If the poles are complex conjugate pole pairs, then the transfer function is:

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 + a(1)s + a(2)} = \frac{1}{(s + \alpha + j\beta)(s + \alpha - j\beta)}$$

- By applying the partial fraction expansion, the transfer function is:

$$H(s) = \frac{1}{(s + \alpha + j\beta)(s + \alpha - j\beta)} = \frac{A_0}{s + \alpha + j\beta} + \frac{A_1}{s + \alpha - j\beta}$$

- The resulting system impulse response is:

$$h(t) = A_0 e^{-\alpha t} e^{j\beta t} + A_1 e^{-\alpha t} e^{-j\beta t}$$

## • Example 5

A system is defined by a transfer function

$$H(s) = \frac{1}{(s+1)}$$

If the input to the system is

$$\begin{aligned} x(t) &= e^{-0.1t} & t \geq 0 \\ &= 0 & t < 0 \end{aligned}$$

Output of the system is

$$Y(s) = H(s)X(s) = \left( \frac{1}{s+1} \right) \left( \frac{1}{s+0.1} \right) = \frac{1}{(s+1)(s+0.1)} = \frac{A_0}{s+1} + \frac{A_1}{s+0.1}$$

Partial  
fraction  
expansion



$$\begin{aligned} Y(s) = \frac{-1.1}{s+1} + \frac{1.1}{s+0.1} &\longrightarrow y(t) = -1.1e^{-1t} + 1.1e^{-0.1t} & t \geq 0 \\ &= 0 & t < 0 \end{aligned}$$

## •Example 6

A transfer function of a system that has a complex conjugate pole pair is defined as:

$$H(s) = \frac{1}{(s + 0.5 + j2\pi 100)(s + 0.5 - j2\pi 100)}$$

Partial  
fraction  
expansion

Solving the partial fraction expansion results in:

$$H(s) = \frac{1}{(s + 0.5 + j2\pi 100)(s + 0.5 - j2\pi 100)} = \frac{A_0}{s + 0.5 + j2\pi 100} + \frac{A_1}{s + 0.5 - j2\pi 100}$$

$$h(t) = \left( -\frac{1}{j4\pi 100} \right) e^{-0.5t} e^{-j2\pi 100t} + \left( \frac{1}{j4\pi 100} \right) e^{-0.5t} e^{j2\pi 100t}$$

$$= \left( \frac{1}{2\pi 100} \right) e^{-0.5t} \sin(2\pi 100t) \quad t \geq 0$$

$$= 0 \quad t < 0$$

# RELATIONSHIP BETWEEN LAPLACE AND FOURIER TRANSFORM

- The Fourier transform can be obtained from the Laplace transform by making the substitution  $s = j\omega = j2\pi f$ .
- A transfer function is

$$H(s) = \frac{1}{(s^2 + s + (2\pi 100)^2)}$$

By making the substitution  $s = j\omega = j2\pi f$ , the Fourier transform of the transfer function is

$$H(f) = \frac{1}{(-(2\pi f)^2 + j2\pi f + (2\pi 100)^2)} = \frac{1}{((2\pi 100)^2 - (2\pi f)^2) + j2\pi f}$$

# RELATIONSHIP BETWEEN LAPLACE AND FOURIER TRANSFORM

- The Fourier transform when defined in terms of the magnitude and phase is

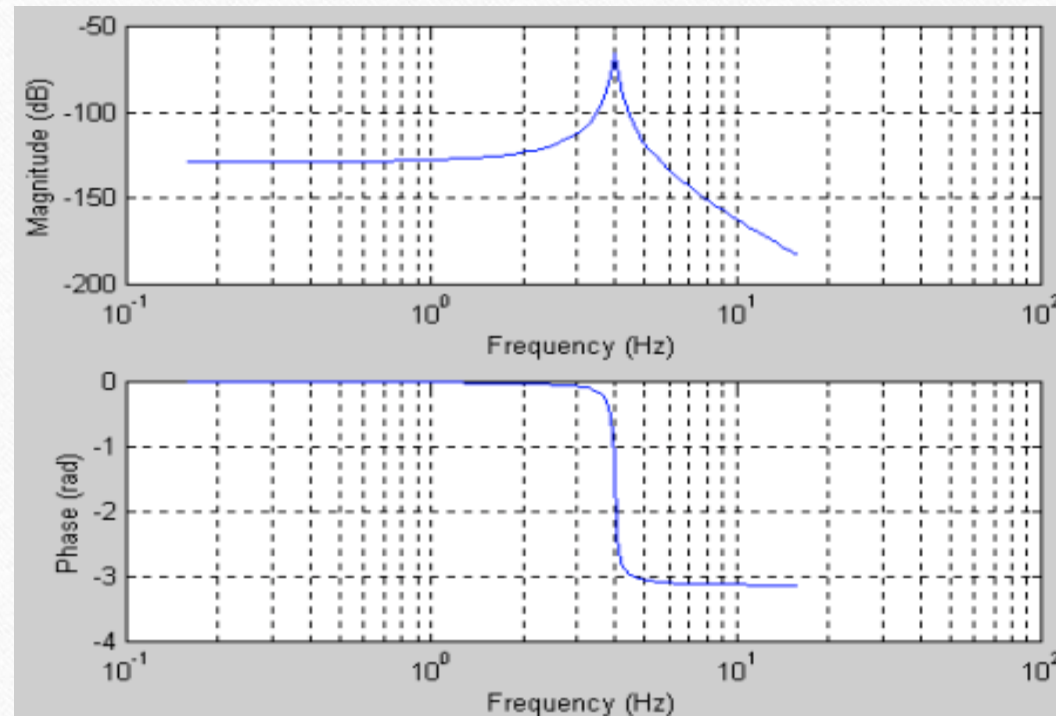
$$|H(f)| = \frac{1}{\sqrt{((2\pi 100)^2 - (2\pi f)^2)^2 + (2\pi f)^2}}$$

**Magnitude**

$$\phi(f) = -\tan^{-1}\left(\frac{2\pi f}{(2\pi 100)^2 - (2\pi f)^2}\right)$$

**Phase**

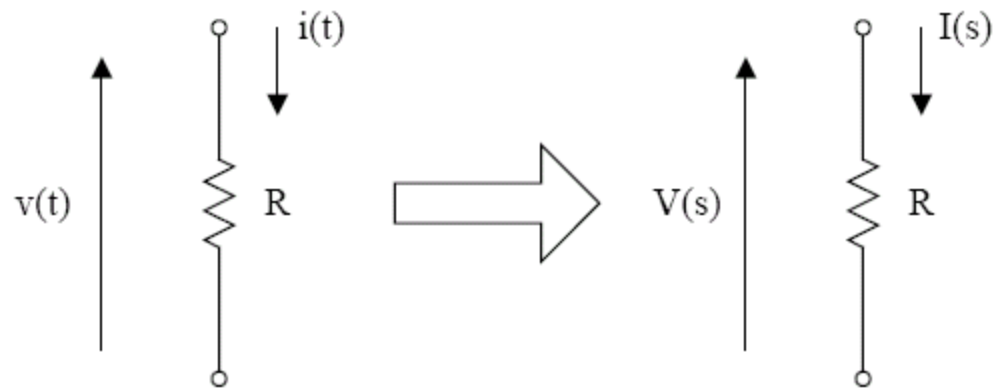
# FREQUENCY RESPONSE OF TRANSFER FUNCTION



Magnitude and phase plot of transfer function

# Circuit Analysis using Laplace Transform

## a) Resistor



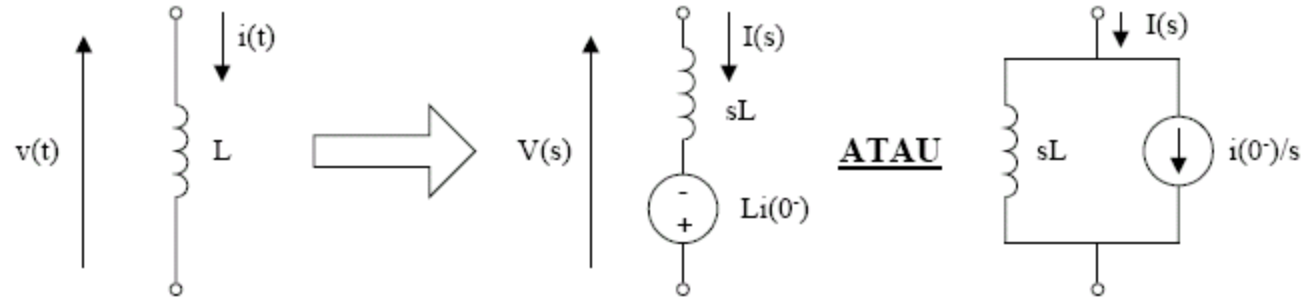
Time domain

S-domain

$$v(t) = i(t) R \quad \Leftrightarrow \quad V(s) = I(s) R$$



## b) Inductor



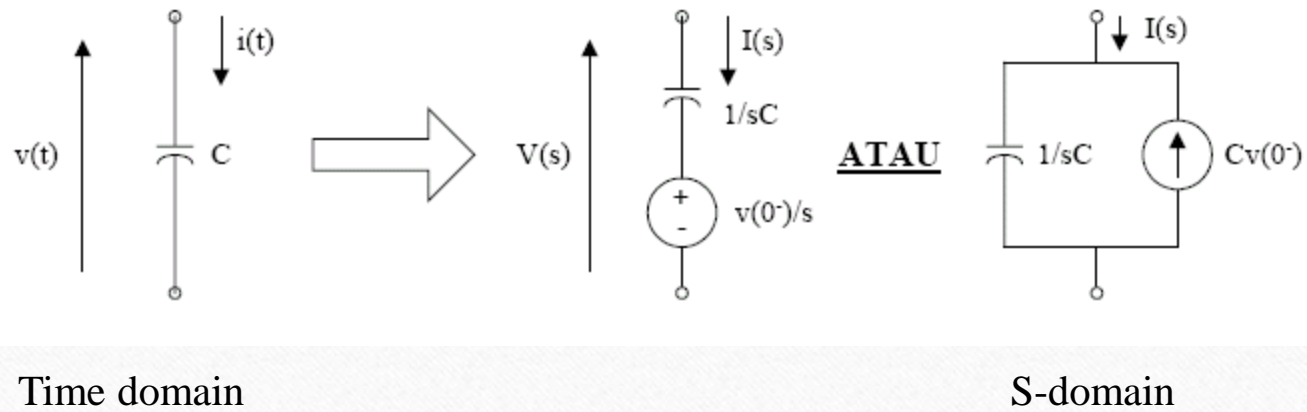
Time domain

S-domain

$$v(t) = L \frac{di(t)}{dt} \quad \Leftrightarrow \quad V(s) = s L I(s) - L i(0^-)$$

$$I(s) = \frac{1}{sL} V(s) + \frac{1}{s} i(0^-)$$

## b) Capacitor



$$v(t) = \frac{1}{C} \int i(t) dt$$

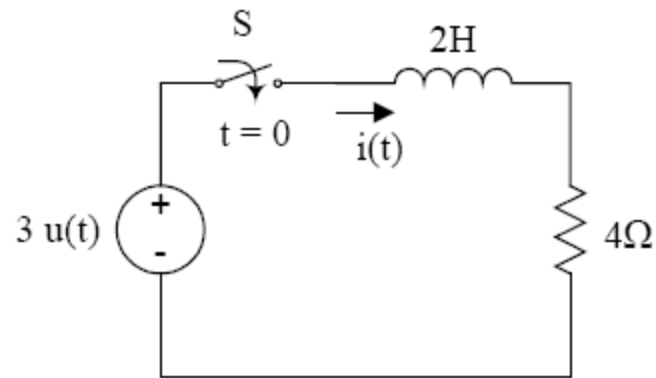
$$\Leftrightarrow V(s) = \frac{1}{sC} I(s) + \frac{v(0^-)}{s}$$

$$i(t) = C \frac{dv(t)}{dt}$$

$$I(s) = sC V(s) - C v(0^-)$$

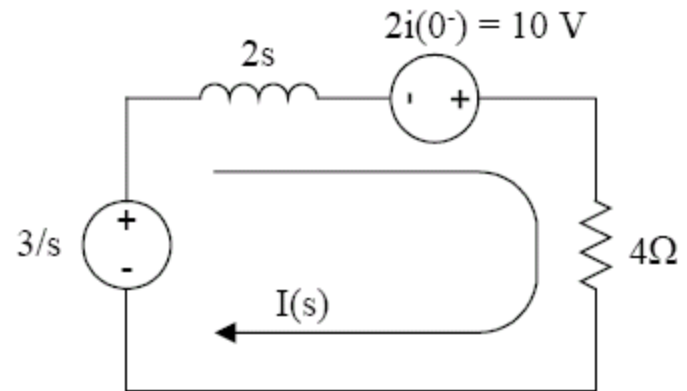
### Example 7

Determine  $i(t)$  when switch  $S$  in the circuit was closed when  $t \geq 0$ s. Given the the start value of  $i(t)$ ,  $i(0^-) = 5\text{A}$ .



## Solution

The s-domain circuit is:



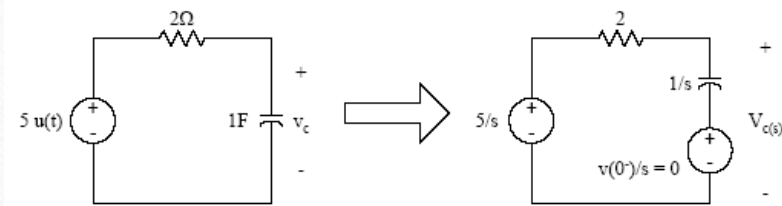
$$(2s + 4) I(s) = \frac{3}{s} + 10$$

Inverse laplace transform

$$I(s) = \frac{3 + 10s}{s(4 + 2s)} \longrightarrow \therefore i(t) = \underline{0.75 u(t) + 4.25 e^{-2t} u(t)}$$

# Solution

- At  $0 \leq t \leq 1$



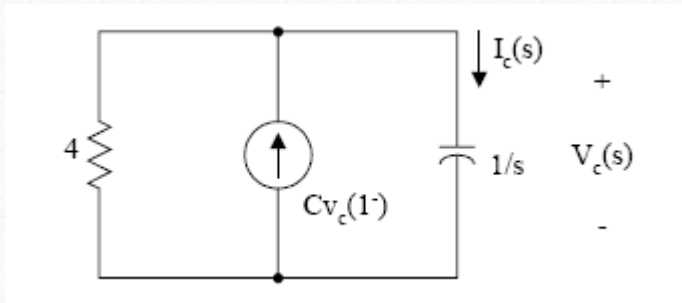
$$\begin{aligned} V_C(S) &= \frac{1/S}{2 + 1/S} \left( \frac{5}{S} \right) \\ &= \frac{5}{(2S + 1)S} \\ &= \frac{2.5}{S(S + 0.5)} \\ &= \frac{A}{S} + \frac{B}{S + 0.5} \end{aligned}$$

$$A = \left. \frac{2.5}{S + 0.5} \right|_{S=0} = 5$$

$$B = \left. \frac{2.5}{S} \right|_{S=0.5} = -5$$

$$V_C(t) = 5u(t) - 5e^{-0.5t}u(t)$$

- At  $t \geq 1$



$$\begin{aligned} V_c(1^-) &= 5u(t) - 5e^{-0.5t}u(t) \\ &= 5 - 5e^{-0.5} \\ &= 1.967V \end{aligned}$$

$$\begin{aligned} I_c(S) &= \frac{4}{4 + 1/S} (1.967) \\ &= \frac{S(1.967)}{S + 0.25} \end{aligned}$$

$$\begin{aligned} V_c(S) &= \frac{I_c(S)}{S} \\ &= \frac{1.967}{S + 0.25} \end{aligned}$$

- For  $t' \geq 1$  where  $t' = t - 1$

$$V_c(t') = 1.967e^{-0.25t'}u(t')$$

$$V_c(t-1) = 1.967e^{-0.25(t-1)}u(t-1)$$