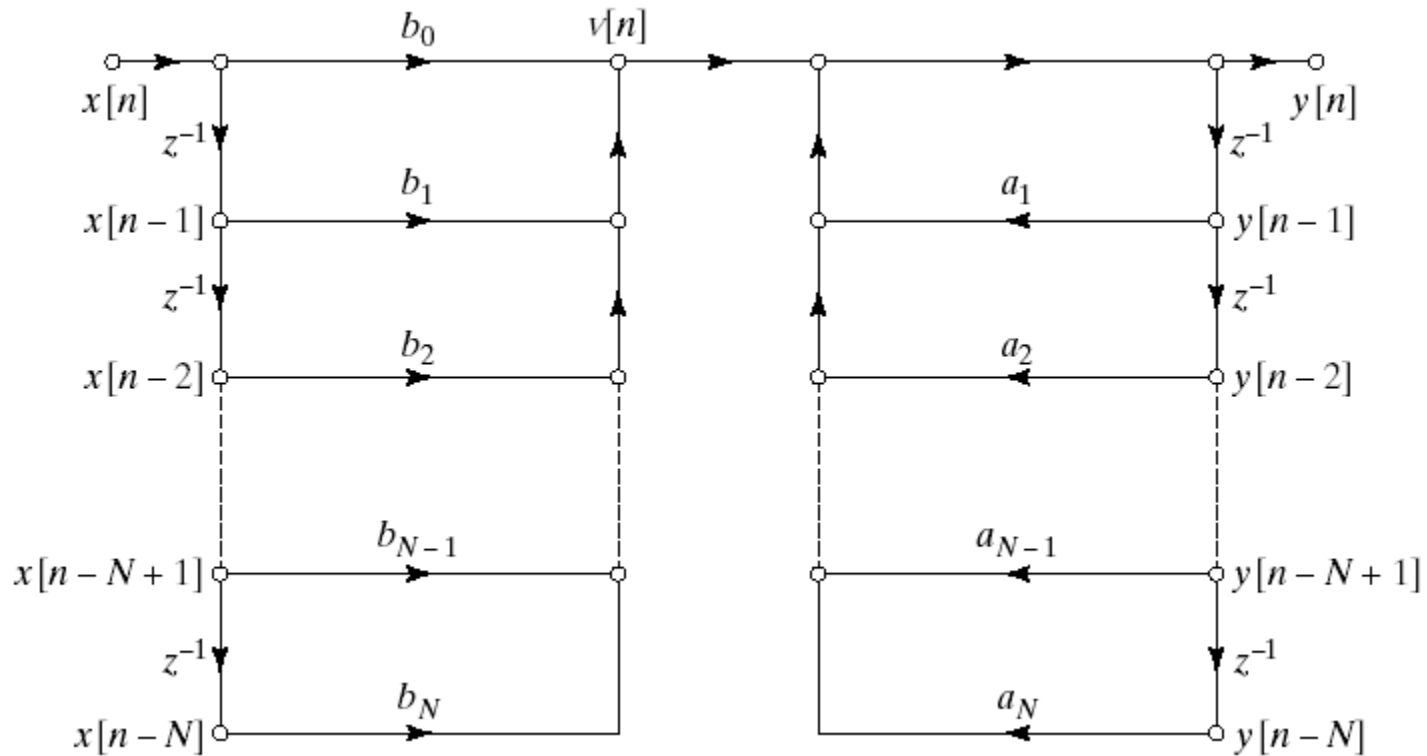


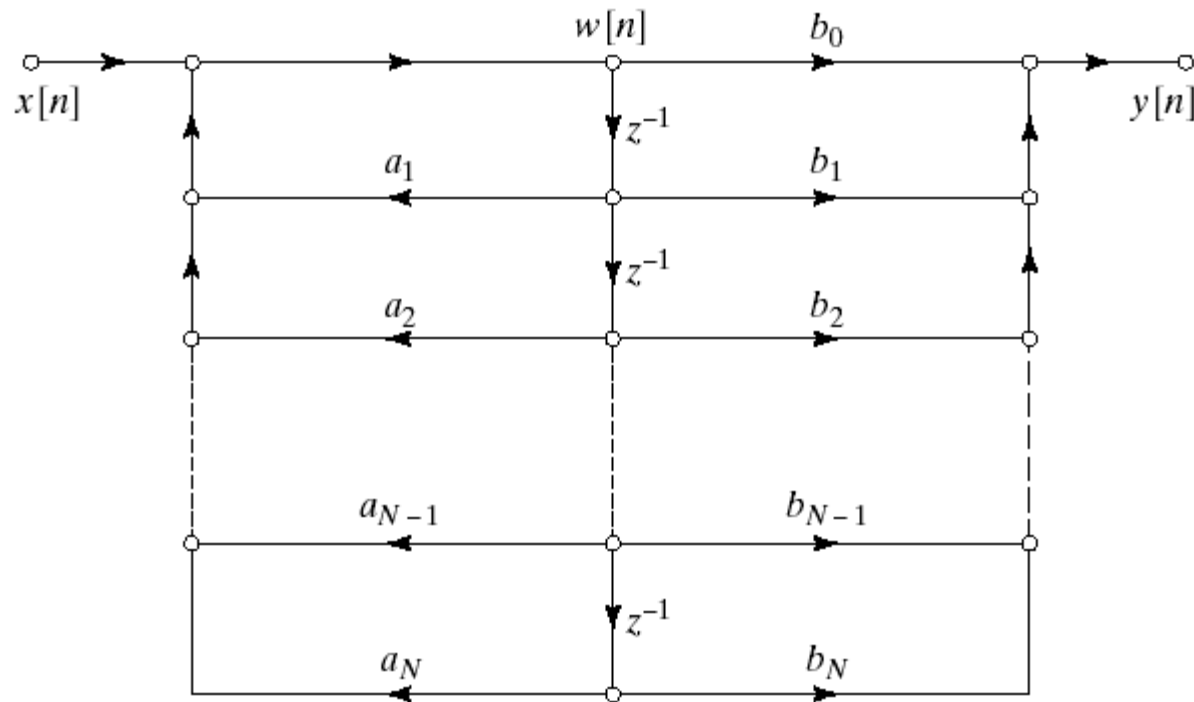
IIR SYSTEMS



Basic Structures for IIR Systems: Direct Form I



Basic Structures for IIR Systems: Direct Form II



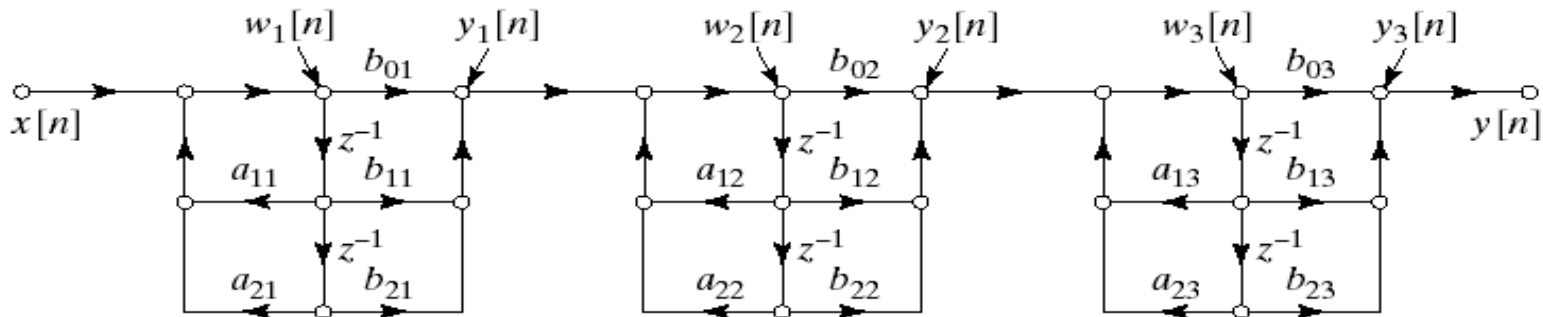
Basic Structures for IIR Systems: Cascade Form

- General form for cascade implementation

$$H(z) = A \frac{\prod_{k=1}^{M_1} (1 - f_k z^{-1}) \prod_{k=1}^{M_2} (1 - g_k z^{-1})(1 - g_k^* z^{-1})}{\prod_{k=1}^{N_1} (1 - c_k z^{-1}) \prod_{k=1}^{N_2} (1 - d_k z^{-1})(1 - d_k^* z^{-1})}$$

$$H(z) = \prod_{k=1}^{M_1} \frac{b_{0k} + b_{1k} z^{-1} - b_{2k} z^{-2}}{1 - a_{1k} z^{-1} - a_{2k} z^{-2}}$$

- More practical form in 2nd order systems

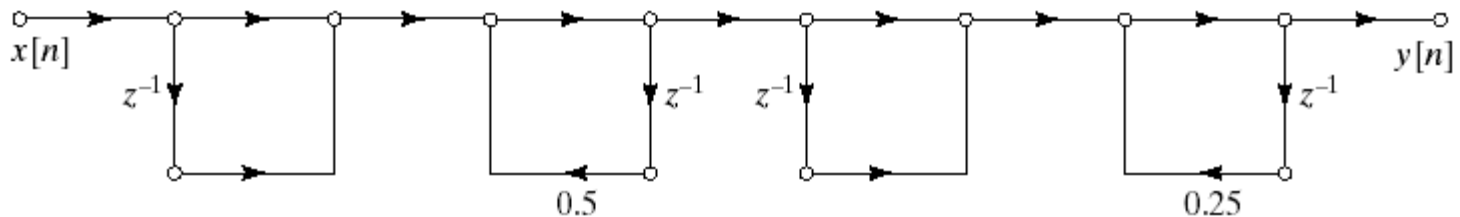


Example

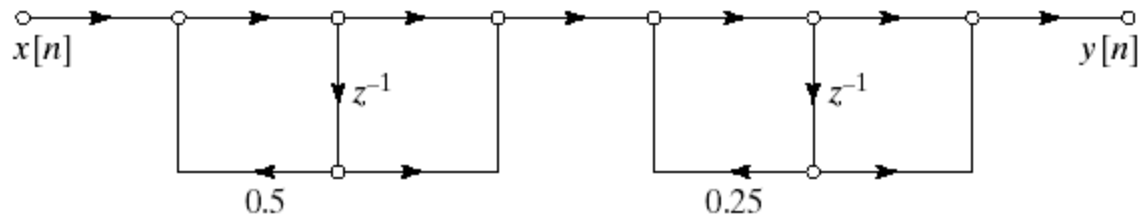
$$H(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - 0.75z^{-1} + 0.125z^{-2}} = \frac{(1 + z^{-1})(1 + z^{-1})}{(1 - 0.5z^{-1})(1 - 0.25z^{-1})}$$

$$= \frac{(1 + z^{-1})(1 + z^{-1})}{(1 - 0.5z^{-1})(1 - 0.25z^{-1})}$$

- Cascade of Direct Form I subsections



- Cascade of Direct Form II subsections



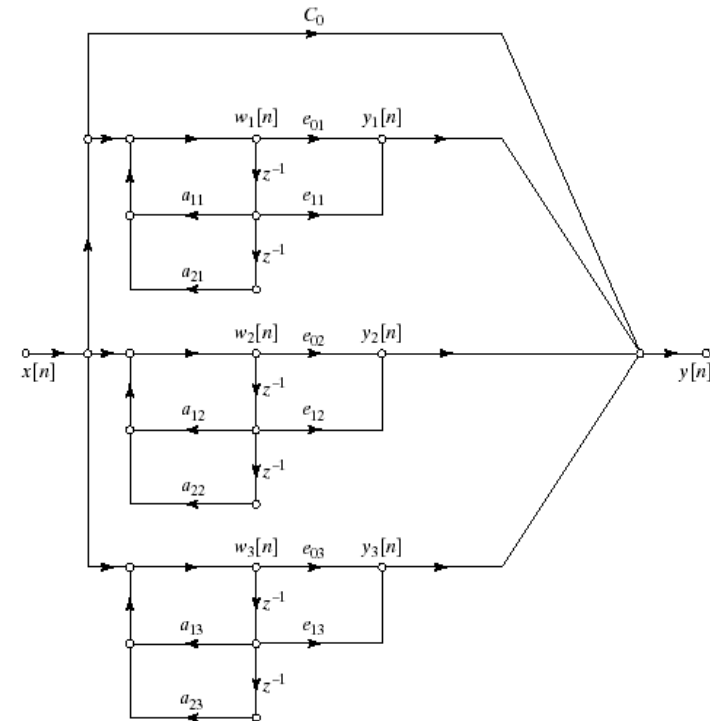
Basic Structures for IIR Systems: Parallel Form

- Represent system function using partial fraction expansion

$$H(z) = \sum_{k=0}^{N_p} C_k z^{-k} + \sum_{k=1}^{N_p} \frac{A_k}{1 - c_k z^{-1}} + \sum_{k=1}^{N_p} \frac{B_k (1 - e_k z^{-1})}{(1 - d_k z^{-1})(1 - d_k^* z^{-1})}$$

- Or by pairing the real poles

$$H(z) = \sum_{k=0}^{N_p} C_k z^{-k} + \sum_{k=1}^{N_s} \frac{e_{0k} + e_{1k} z^{-1}}{1 - a_{1k} z^{-1} - a_{2k} z^{-2}}$$

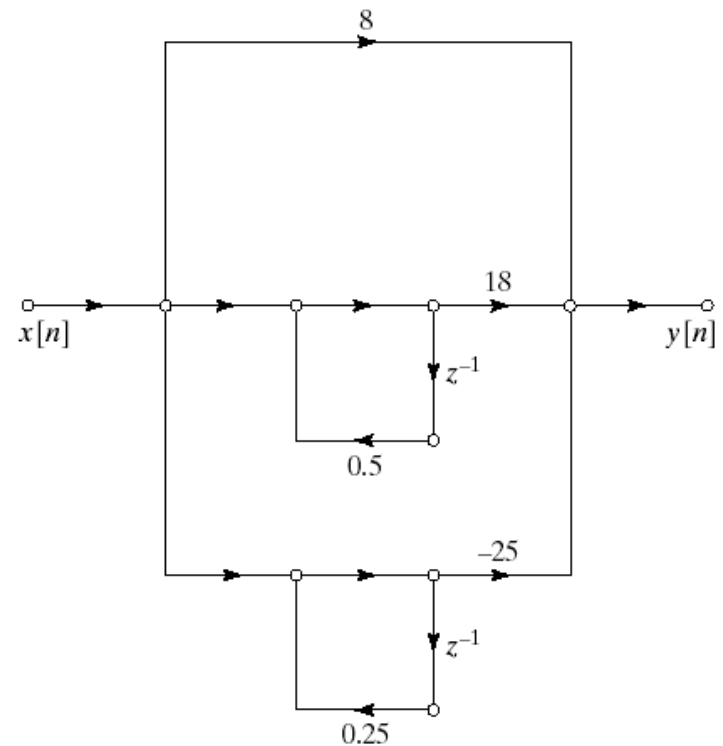
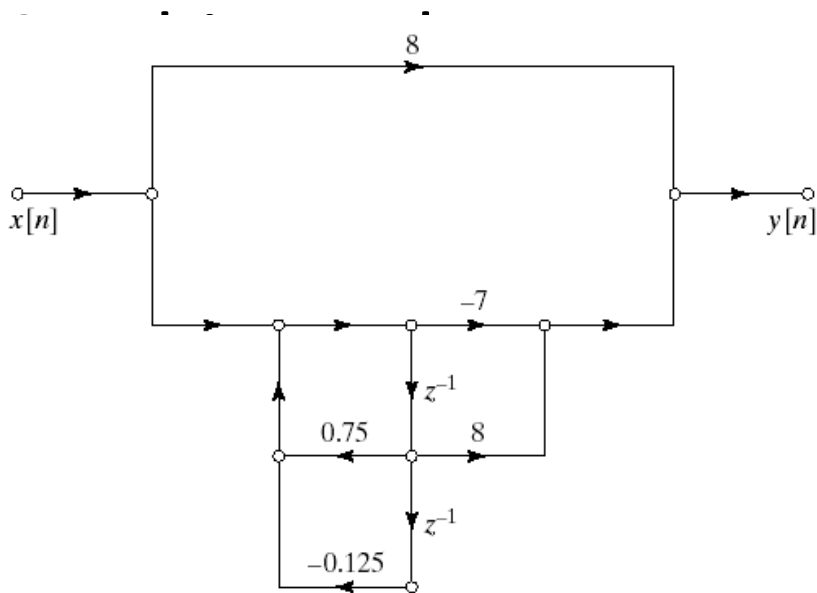


Example

- Partial Fraction Expansion

$$H(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - 0.75z^{-1} + 0.125z^{-2}} = 8 + \frac{18}{(1 - 0.5z^{-1})} - \frac{25}{(1 - 0.25z^{-1})}$$

$$H(z) = 8 + \frac{-7 + 8z^{-1}}{1 - 0.75z^{-1} + 0.125z^{-2}}$$

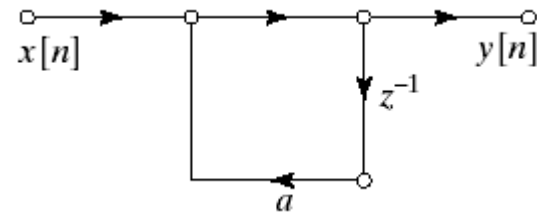


Transposed Forms

- Linear signal flow graph property:
 - Transposing doesn't change the input-output relation

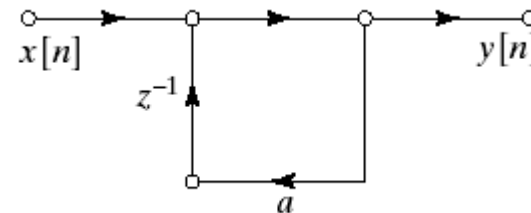
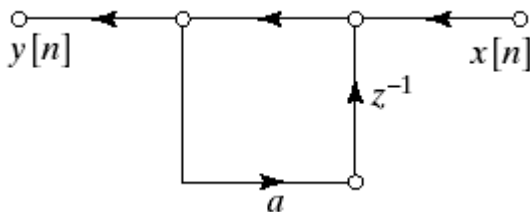
- Transposing:

- Reverse directions of all branches
- Interchange input and output nodes



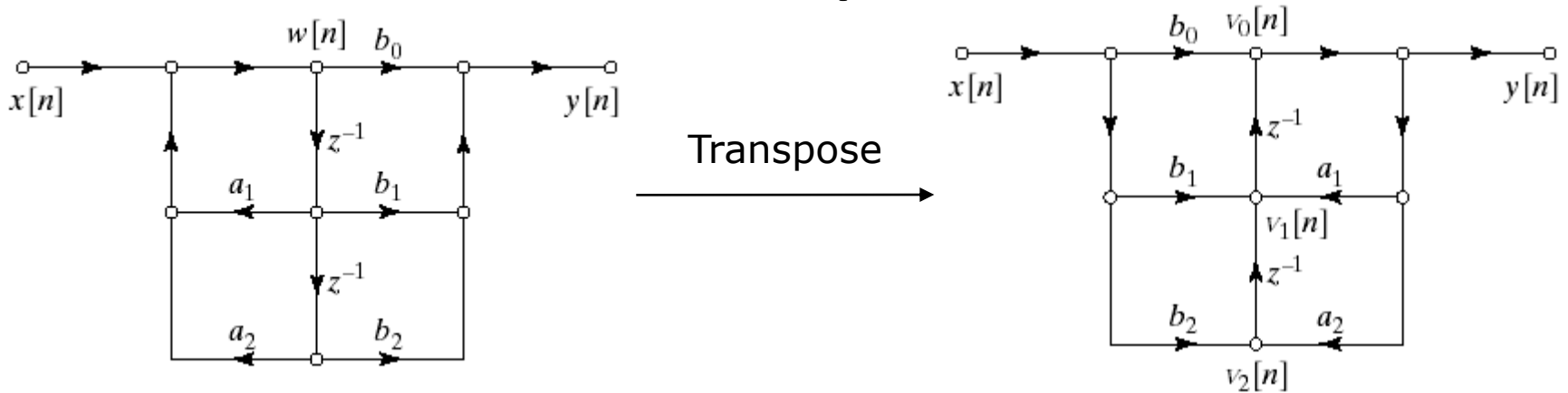
- Example:

$$H(z) = \frac{1}{1 - az^{-1}}$$



- Reverse directions of branches and interchange input and output

Example



$$y[n] = a_1 y[n-1] + a_2 y[n-2] + b_0 x[n] + b_1 x[n-1] + b_2 x[n-2]$$

- Both have the same system function or difference equation