SOFTWARE ENGINEERING



Real-Time Systems Design and Analysis

BASIC REAL-TIME CONCEPTS

o Terminology

- Real-time design issues
- Example real-time systems
- Common misconceptions
- Brief history

TERMINOLOGY

- Systems concepts
- Real-time definitions
- Events and determinism
- CPU utilization

SYSTEMS CONCEPTS

Definition: A system is a mapping of a set of inputs into a set of outputs.



A system with *n* inputs and *m* outputs.

SYSTEMS CONCEPTS



Typical real-time control system including inputs from sensors and imaging devices and producing control signals and display information.

SYSTEMS CONCEPTS

Definition: The time between the presentation of a set of inputs to a system (stimulus) and the realization of the required behavior, including the availability of all associated outputs, (response) is called the response time of the system.

Definition: A real-time system is a system that must satisfy explicit (bounded) response-time constraints or risk severe consequences, including failure.

Definition: A failed system is a system that cannot satisfy one or more of the requirements stipulated in the formal system specification.

Definition: A real-time system is one whose logical correctness is based on both the correctness of the outputs and their timeliness.

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Definition: A soft real-time system is one in which performance is degraded but not destroyed by failure to meet response-time constraints.

Definition: A hard real-time system is one in which failure to meet a single deadline may lead to complete and catastrophic system failure.

Definition: A firm real-time system is one in which a few missed deadlines will not lead to total failure, but missing more than a few may lead to complete and catastrophic system failure.

	Real-time Classification	Explanation	
Automated teller machine	soft	Missing even many	
		deadlines will not lead to	
		catastrophic failure, only	
		degraded performance.	
Embedded navigation	firm	Missing critical navigation	
controller for autonomous		deadlines causes the robot	
robot weed killer		to veer hopelessly out of	
		control and damage crops.	
Avionics weapons delivery	hard	Missing the deadline to	
system in which pressing a		launch the missile within a	
button launches an air-to-		specified time after pressing	
air missile		the button can cause the	
		target to be missed – which	
		will result in catastrophe.	

A sampling of hard, soft, and firm realtime systems.

Definition: Any occurrence that causes the program counter to change nonsequentially is considered a change of flow-of-control, and thus an event.



A simple program flowchart showing a branch as a change in flow of control, represented by the diamond icon.

Definition: The release time is the time at which an instance of a scheduled task is ready to run, and is generally associated with an interrupt.

	Periodic	Aperiodic	Sporadic
		m · 11 1	
Synchronous	Cyclic Code	Typical branch	Branch
	Processes		error recovery
	scheduled by	Garbage	
	internal clock	collection	Traps
Asynchronous	Clock generated interrupt	Regular, but not fixed period interrupt	Externally generated exception
			"Random events"

Taxonomy of events and some examples.

Definition: A system is deterministic if, for each possible state and each set of inputs, a unique set of outputs and next state of the system can be determined.

Note, deliberately non-deterministic machines are hard to build, while it is easy to fall into accidentally nondeterministic machines!

Definition: The (CPU) utilization or time-loading factor, , is a measure of the percentage of non-idle processing.

Utilization (%)	Zone Type	Typical Application
0-25	significant excess	various
	processing power – CPU	
	may be more powerful than	
	necessary	
26-50	very safe	various
51-68	safe	various
69	theoretical limit	embedded systems
70-82	questionable	embedded systems
83-99	dangerous	embedded systems
100+	overload	stressed systems

CPU utilization zones and typical applications and recommendations.

Determining CPU Utilization

Suppose a system has $n \ge 1$ periodic tasks, each with an execution period of p_i and hence execution frequency $f_i = 1/p_i$. If task *i* is known to have (or has been estimated to have) a maximum (worst case) execution time of e_i then the utilization factor u_i for task *i* is

$$u_i = e_i / p_i \tag{1.1}$$

Then the overall system utilization is

$$U = \sum_{i=1}^{n} u_i = \sum_{i=1}^{n} e_i / p_i$$
(1.2)

- The nature of time
 - Where do deadlines come from?
 - Challenge "conventional" wisdom as it may place undue constraints on the system
 - Clocks can be used for time stamping and synchronization, but clocks are imperfect

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REAL-TIME DESIGN ISSUES



Disciplines that impact real-time systems.

REAL-TIME DESIGN ISSUES

- The selection of hardware and software, and evaluation of the tradeoff needed for a costeffective solution, including dealing with distributed computing systems and the issues of parallelism and synchronization.
- Specification and design of real-time systems and correct representation of temporal behavior.
- Understanding the nuances of the programming language(s) and the real-time implications resulting from their translation into machine code.

REAL-TIME DESIGN ISSUES

- Maximizing of system fault tolerance and reliability through careful design.
- The design and administration of tests, and the selection of test and development equipment.
- Taking advantage of open systems technology and interoperability.
- Measuring and predicting response time and reducing it.
- Performing a schedulability analysis, that is, determining and guaranteeing deadline satisfaction, *a priori*, is largely "just" scheduling theory.

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EXAMPLE REAL-TIME SYSTEMS

Domain	Applications
Avionics	NavigationDisplays
Multimedia	GamesSimulators
Medicine	Robot surgeryRemote surgeryMedical imaging
Industrial Systems	Robotic assembly linesAutomated inspection
Civilian	Elevator controlAutomotive systems

Real-time application domains.

EXAMPLE REAL-TIME SYSTEMS

- Aircraft inertial measurement system
- Nuclear plant control
- Airline reservation system
- Pasta sauce bottling plant
- Traffic light control system for 4-way intersection

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COMMON MISCONCEPTIONS

- Real-time systems are synonymous with "fast" systems.
- Rate-monotonic analysis has solved "the realtime problem."
- There are universal, widely accepted methodologies for real-time systems specification and design.
- There is never a need to build a real-time operating system, because many commercial products exist.
- The study of real-time systems is mostly about scheduling theory.

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BRIEF HISTORY

Year	Landmark	Developer	Development	Innovations
1947	Whirlwind	MIT/US Navy	Flight simulator	Ferrite core
				memory, "real
				response times"
1957	SAGE	IBM	Air defense	Specifically
				designed for real-
				time
1958	Scientific 1103A	Univac	General purpose	Hardware interrupt
1959	SABRE	IBM	Airline reservation	Hub-go-ahead
				policy
1962	Basic Executive	IBM	General purpose	First real-time
				executive
1963	Basic Executive II	IBM	General purpose	Diverse real-time
				scheduling,
				Disk resident
				user/systems
				programs
1970s	RSX, RTE	DEC, HP	Real-time	Hosted by mini-
			operating systems	computers
1973	Rate-monotonic	Liu and Layland	Theory	Stated upper
	system			bound on
				utilization for
				schedulable
1000				systems
1980s	RMX-80, MROS	Various	Real-time	Hosted by
1000	68K, VRTX, etc.		operating system	microprocessors
1983	Ada 83	US Department of	Programming	Intended for
		Defense	language	mission critical,
				embedded, real-
				time systems
1995	Ada 95	Community	Programming	Refinement to Ada
			Language	83