



Digital Signal  
Processing- Lecture 3

# Topics to be covered:

- **Energy & Power Signals**
- **Basic operations on the signal**

## Energy and Power Signals

The total energy of a continuous time signal  $x(t)$  is defined as

$$E_x = \lim_{T \rightarrow \infty} \int_{-T}^T x^2(t) dt = \int_{-\infty}^{\infty} x^2(t) dt$$

And its average power is

$$P_x = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt$$

In the case of a discrete time signal  $x[nT]$ , the total energy of the

$$E_{dx} = T \sum_{n=-\infty}^{\infty} |x[nT]|^2$$

And its average power is defined by

$$P_{dx} = \lim_{N \rightarrow \infty} \left( \frac{1}{2N+1} \right) \sum_{n=-N}^N |x[nT]|^2$$

## Energy and Power Signals

- A signal is referred to as an energy signal, if and only if the total energy of the signal satisfies the condition

$$0 < E < \infty$$

- On the other hand, it is referred to as a power signal, if and only if the average power of the signal satisfies the condition

$$0 < P < \infty$$

- An energy signal has zero average power, whereas a power signal has infinite energy.

- Periodic signals and random signals are usually viewed as power signals, whereas signals that are both deterministic and non-periodic are energy signals.

### Example 1:

Compute the signal energy and signal power for

$$x[nT] = (-0.5)^n u(nT), \quad T = 0.01 \text{ seconds}$$

**Solution:**

$$\begin{aligned} E_{dx} &= \lim_{N \rightarrow \infty} T \sum_{n=-N}^N |x(nT)|^2 = 0.01 \sum_{n=0}^{\infty} |(-0.5)^n|^2 \\ &= 0.01 \sum_{n=0}^{\infty} (-0.5)^{2n} = 0.01 \sum_{n=0}^{\infty} 0.25^n \\ &= 0.01 [1 + 0.25 + (0.25)^2 + (0.25)^3 + \dots] \\ &= \frac{0.01}{1 - 0.25} = 1/75 \end{aligned}$$

Since  $E_{dx}$  is finite, the signal power is zero.

## Example2:

Repeat Example1 for  $y[nT] = 2e^{j3n}u[nT]$ ,  $T = 0.2$  second.

## Solution:

$$\begin{aligned} P_{dx} &= \lim_{N \rightarrow \infty} \left( \frac{1}{2N+1} \right) \sum_{n=-N}^N |y(nT)|^2 = \lim_{N \rightarrow \infty} \left( \frac{1}{2N+1} \right) \sum_{n=0}^N |2e^{j3n}|^2 \\ &= \lim_{N \rightarrow \infty} \left( \frac{1}{2N+1} \right) \sum_{n=0}^N 2^2 = \lim_{N \rightarrow \infty} \frac{4}{2N+1} \sum_{n=0}^N 1 = \lim_{N \rightarrow \infty} \frac{4(N+1)}{2N+1} \\ &= \lim_{N \rightarrow \infty} 4 \left( \frac{N}{2N+1} + \frac{1}{2N+1} \right) = 4 \times \frac{1}{2} = 2 \end{aligned}$$

# Basic Operations on Signals

## (a) Operations performed on dependent variables

### 1. Amplitude Scaling:

let  $x(t)$  denote a continuous time signal. The signal  $y(t)$  resulting from amplitude scaling applied to  $x(t)$  is defined by

$$y(t) = cx(t)$$

where  $c$  is the scale factor.

In a similar manner to the above equation, for discrete time signals we write

$$y[nT] = cx[nT]$$



## **(b) Operations performed on independent variable**

- **Time Scaling:**

Let  $y(t)$  is a compressed version of  $x(t)$ . The signal  $y(t)$  obtained by scaling the independent variable, time  $t$ , by a factor  $k$  is defined by

$$y(t) = x(kt)$$

- if  $k > 1$ , the signal  $y(t)$  is a compressed version of  $x(t)$ .
- If, on the other hand,  $0 < k < 1$ , the signal  $y(t)$  is an expanded (stretched) version of  $x(t)$ .



## Example of time scaling

