# TSN: Lecture 19 NRZ

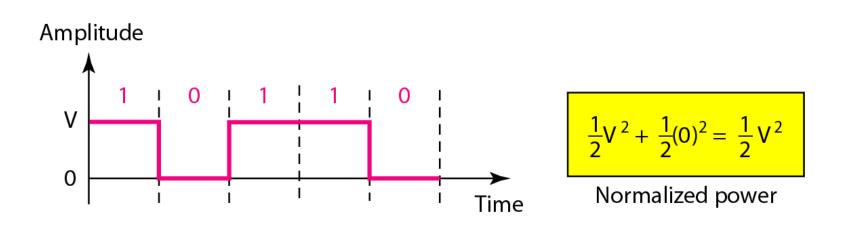
# **Topics Covered**

- Unipolar
- Polar NRZ
- Polar RZ

# Unipolar

- All signal levels are on one side of the time axis either above or below
- NRZ Non Return to Zero scheme is an example of this code. The signal level does not return to zero during a symbol transmission.
- Scheme is prone to baseline wandering and DC components. It has no synchronization or any error detection. It is simple but costly in power consumption.

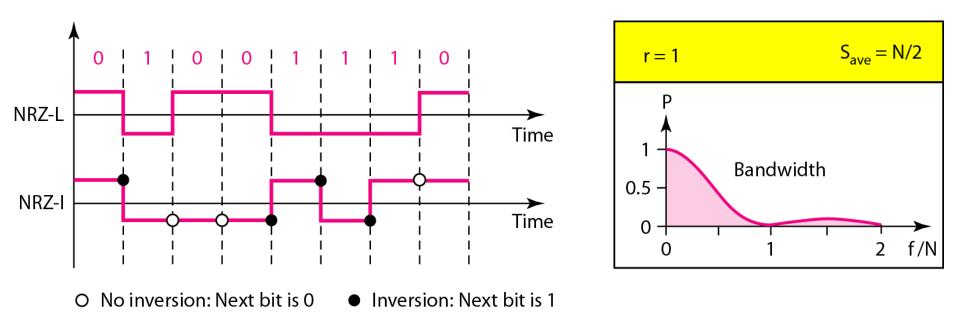
#### Figure 4.5 Unipolar NRZ scheme



## Polar - NRZ

- The voltages are on both sides of the time axis.
- Polar NRZ scheme can be implemented with two voltages. E.g. +V for 1 and -V for 0.
- There are two versions:
  - NZR Level (NRZ-L) positive voltage for one symbol and negative for the other
  - NRZ Inversion (NRZ-I) the change or lack of change in polarity determines the value of a symbol. E.g. a "1" symbol inverts the polarity a "o" does not.

#### Figure 4.6 Polar NRZ-L and NRZ-I schemes





## In NRZ-L the level of the voltage determines the value of the bit. In NRZ-I the inversion or the lack of inversion determines the value of the bit.



# NRZ-L and NRZ-I both have an average signal rate of N/2 Bd.



## NRZ-L and NRZ-I both have a DC component problem and baseline wandering, it is worse for NRZ-L. Both have no self synchronization &no error detection. Both are relatively simple to implement.

Example 4.4

A system is using NRZ-I to transfer 1-Mbps data. What are the average signal rate and minimum bandwidth?

#### Solution

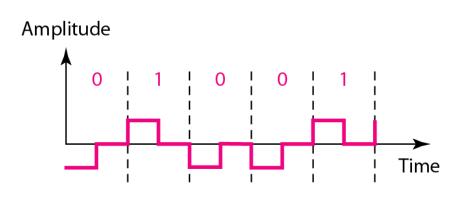
The average signal rate is  $S = c \times N \times R = 1/2 \times N \times 1 = 500$  kbaud. The minimum bandwidth for this average baud rate is Bmin = S = 500 kHz.

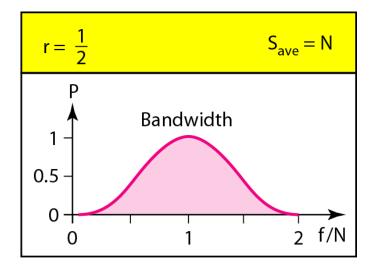
Note c = 1/2 for the avg. case as worst case is 1 and best case is 0

# Polar - RZ

- The Return to Zero (RZ) scheme uses three voltage values. +, o, -.
- Each symbol has a transition in the middle.
  Either from high to zero or from low to zero.
- This scheme has more signal transitions (two per symbol) and therefore requires a wider bandwidth.
- No DC components or baseline wandering.
- Self synchronization transition indicates symbol value.
- More complex as it uses three voltage level. It has no error detection capability.

#### Figure 4.7 Polar RZ scheme

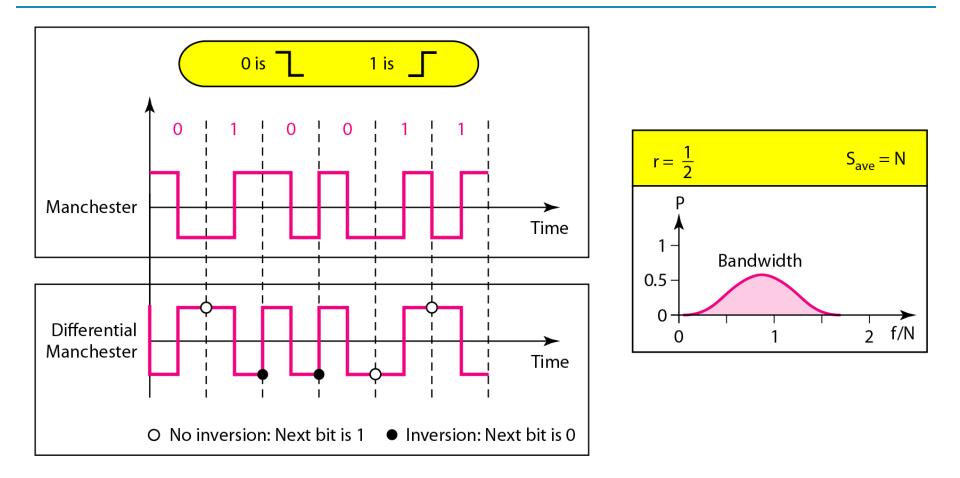




## Polar - Biphase: Manchester and Differential Manchester

- Manchester coding consists of combining the NRZ-L and RZ schemes.
  - Every symbol has a level transition in the middle: from high to low or low to high. Uses only two voltage levels.
- Differential Manchester coding consists of combining the NRZ-I and RZ schemes.
  - Every symbol has a level transition in the middle. But the level at the beginning of the symbol is determined by the symbol value. One symbol causes a level change the other does not.

#### **Figure 4.8** Polar biphase: Manchester and differential Manchester schemes





## In Manchester and differential Manchester encoding, the transition at the middle of the bit is used for synchronization.



The minimum bandwidth of Manchester and differential Manchester is 2 times that of NRZ. The is no DC component and no baseline wandering. None of these codes has error detection.

## **Bipolar - AMI and Pseudoternary**

- Code uses 3 voltage levels: +, o, -, to represent the symbols (note not transitions to zero as in RZ).
- Voltage level for one symbol is at "o" and the other alternates between + & -.
- Bipolar Alternate Mark Inversion (AMI) the "o" symbol is represented by zero voltage and the "1" symbol alternates between +V and -V.
- Pseudoternary is the reverse of AMI.

#### **Figure 4.9** *Bipolar schemes: AMI and pseudoternary*

